

# Conditional Random Fields

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# Overview

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- Sequence Labeling
- Bayesian Networks
- Markov Random Fields
- Conditional Random Fields
- Software example



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# Sequence Labeling Tasks



# Sequence: a sentence

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Pierre  
Vinken  
,  
61  
years  
old  
,  
will  
join  
the  
board  
as  
a  
nonexecutive  
director  
Nov.  
29  
.



# POS Labels

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Pierre	_____	NNP
Vinken	_____	NNP
,	_____	,
61	_____	CD
years	_____	NNS
old	_____	JJ
,	_____	,
will	_____	MD
join	_____	VB
the	_____	DT
board	_____	NN
as	_____	IN
a	_____	DT
nonexecutive	_____	JJ
director	_____	NN
Nov.	_____	NNP
29	_____	CD
.	_____	.



# Chunking

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Task: find phrase boundaries:

[NP He ] [VP reckons ] [NP the current  
account deficit ] [VP will narrow ]  
[PP to ] [NP only £ 1.8 billion ]  
[PP in ] [NP September ] .



# Chunking

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Pierre	_____	B-NP
Vinken	_____	I-NP
,	_____	O
61	_____	B-NP
years	_____	I-NP
old	_____	B-ADJP
,	_____	O
will	_____	B-VP
join	_____	I-VP
the	_____	B-NP
board	_____	I-NP
as	_____	B-PP
a	_____	B-NP
nonexecutive	_____	I-NP
director	_____	I-NP
Nov.	_____	B-NP
29	_____	I-NP
.	_____	O



# Named Entity Tagging

Pierre	_____	B-PERSON
Vinken	_____	I-PERSON
,	_____	O
61	_____	B-DATE:AGE
years	_____	I-DATE:AGE
old	_____	I-DATE:AGE
,	_____	O
will	_____	O
join	_____	O
the	_____	O
board	_____	B-ORG_DESC:OTHER
as	_____	O
a	_____	O
nonexecutive	_____	O
director	_____	B-PER_DESC
Nov.	_____	B-DATE:DATE
29	_____	I-DATE:DATE
.	_____	O





# Supertagging

Pierre	_____	N/N
Vinken	_____	N
,	_____	,
61	_____	N/N
years	_____	N
old	_____	(S[adj]\NP)\NP
,	_____	,
will	_____	(S[dcI]\NP)/(S[b]\NP)
join	_____	((S[b]\NP)/PP)/NP
the	_____	NP[nb]/N
board	_____	N
as	_____	PP/NP
a	_____	NP[nb]/N
nonexecutive	_____	N/N
director	_____	N
Nov.	_____	((S\NP)\(S\NP))/N[num]
29	_____	N[num]
.	_____	.



# Hidden Markov Model



# HMM: just an Application of a Bayes Classifier

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$$(\hat{\pi}_1, \hat{\pi}_2 \dots \hat{\pi}_N) = \arg \max_{\pi_1, \pi_2 \dots \pi_N} [P(x_1, x_2 \dots x_N, \pi_1, \pi_2 \dots \pi_N)]$$



# Decomposition of Probabilities

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$$P(x_1, x_2 \dots x_N, \pi_1, \pi_2 \dots \pi_N)$$
$$= \prod_{i=1}^N P(x_i | \pi_i) P(\pi_i | \pi_{i-1})$$

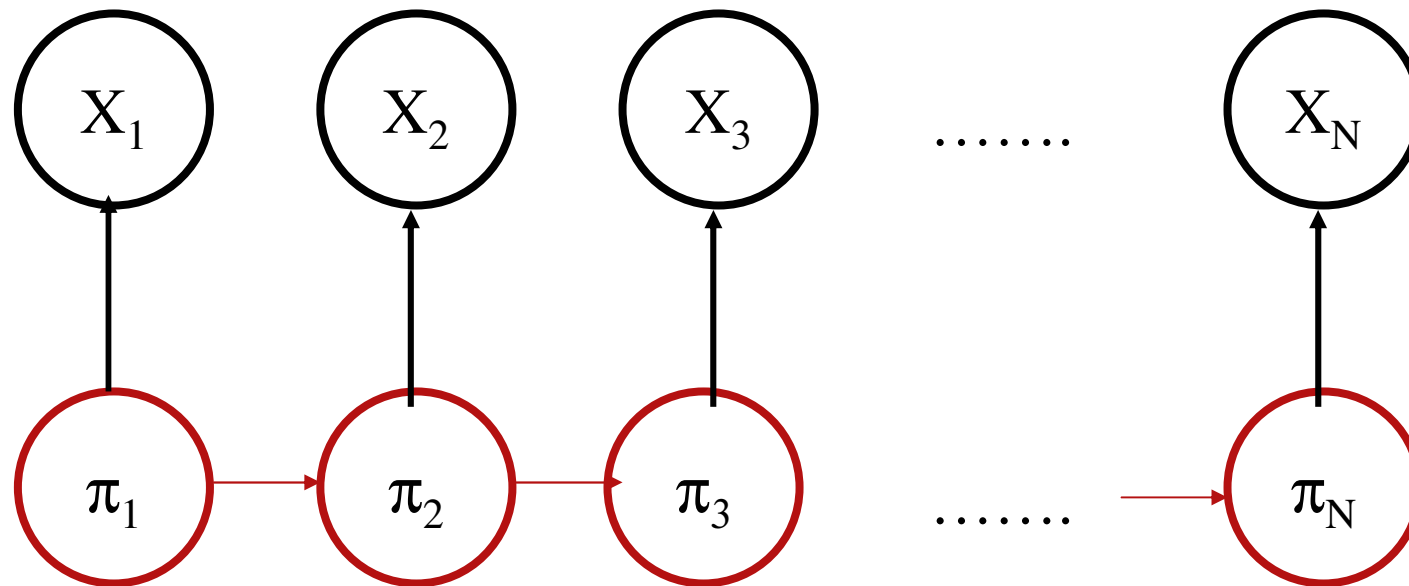
$P(\pi_i | \pi_{i-1})$  : transition probability

$P(x_i | \pi_i)$  : emission probability



# Graphical view HMM

Observation sequence



Label sequence



# Criticism

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- HMMs model only limited dependencies
  - ↳ come up with more flexible models
  - ↳ come up with graphical description



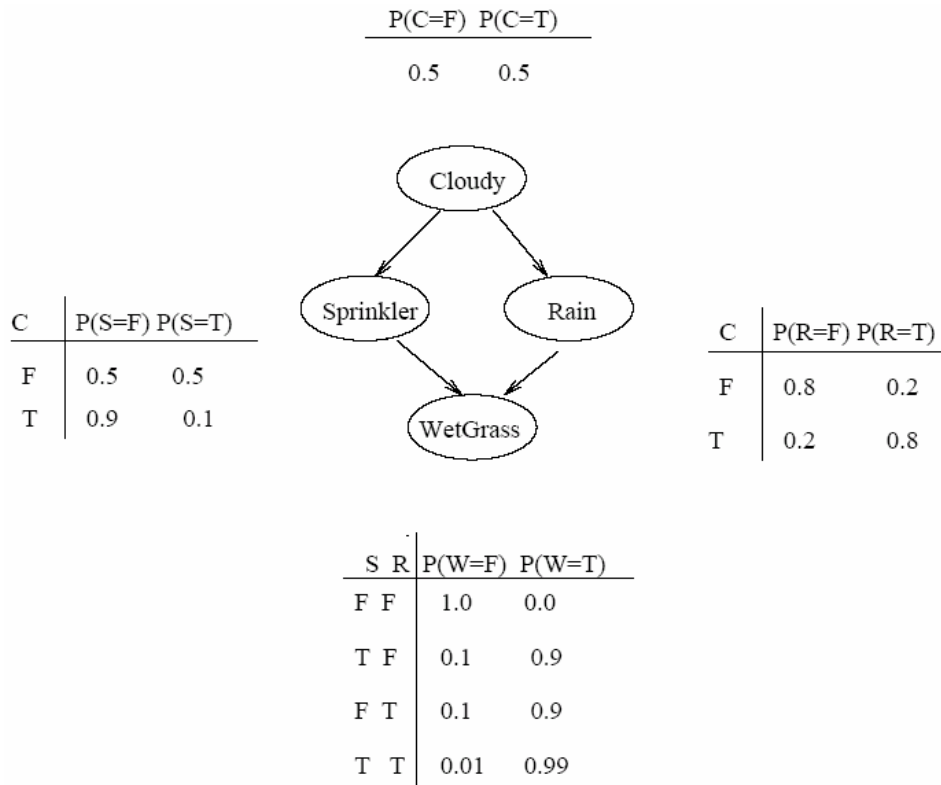
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# Bayesian Networks



# Example for Bayesian Network

From Russel  
and Norvig 95  
AI: A Modern Approach



Corresponding joint  
distribution

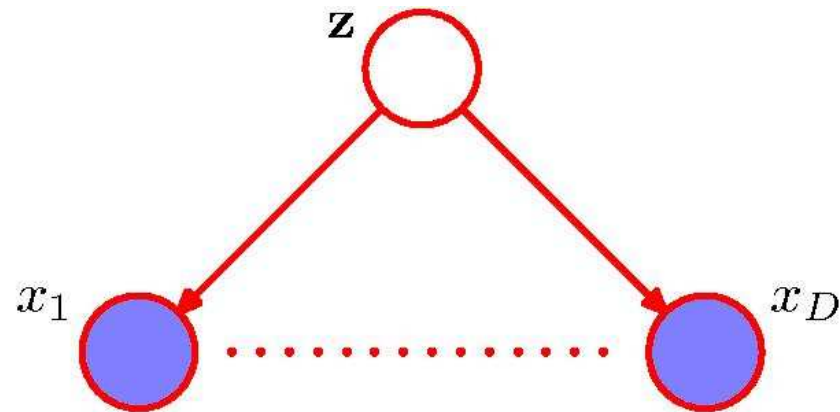
$$P(C, S, R, W) = P(W | S, R)P(S | C)P(R | C)P(C)$$





# Naïve Bayes

Observations  $x_1, \dots, x_D$  are assumed to be independent



$$\prod_{i=1}^D P(x_i | z)$$



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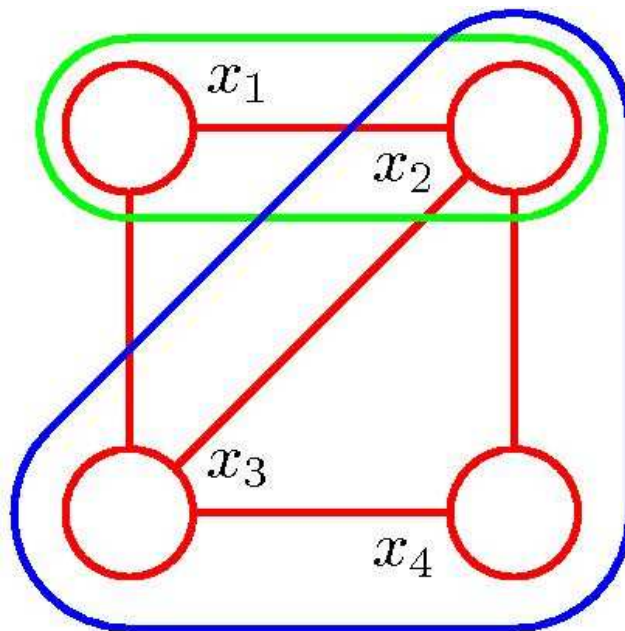
# Markov Random Fields



- Undirected graphical model
- New term:
- *clique* in an undirected graph:
  - Set of nodes such that every node is connected to every other node
- *maximal clique*: there is no node that can be added without add without destroying the clique property



# Example



cliques: green and blue

maximal clique: blue



# Factorization

$x$  : all nodes  $x_1 \dots x_N$

$x_C$  : nodes in clique  $C$

$C_M$  : set of all maximal cliques

$\Psi_C(x_C)$  : potential function ( $\Psi_C(x_C) \geq 0$ )

Joint distribution described by graph

$$p(x) = \frac{1}{Z} \prod_{C \in C_M} \Psi_C(x_C)$$

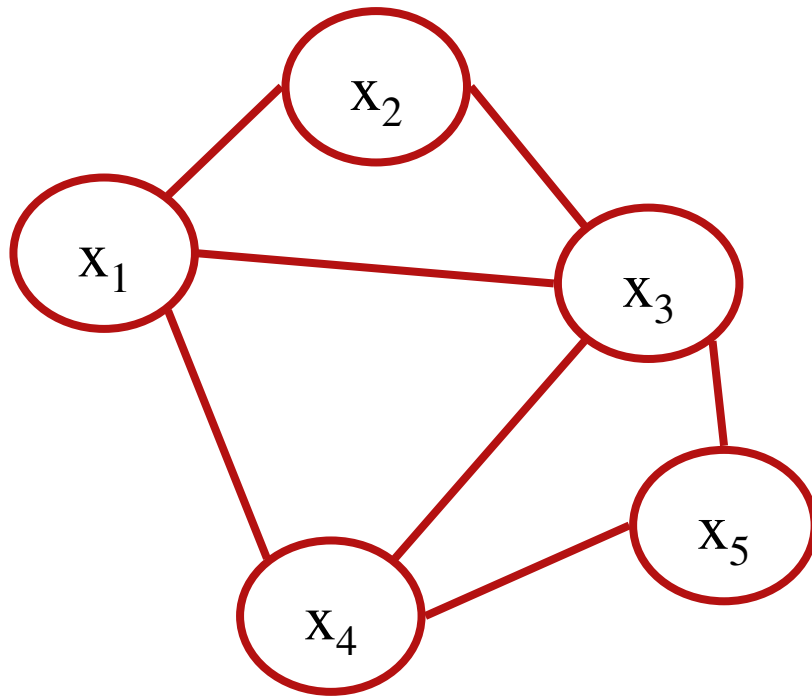
Normalization

$$Z = \sum_x \prod_{C \in C_M} \Psi_C(x_C)$$

$Z$  is sometimes call the *partition function*



# Example



What are the maximum cliques?  
Write down joint probability  
described by this graph

↳ white board



# Energy Function

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Define

$$\Psi_C(x_C) = e^{-E(x_C)}$$

Insert into joint distribution

$$p(x) = \frac{1}{Z} e^{-\sum_{C \in C_M} E(x_C)}$$



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# Conditional Random Fields

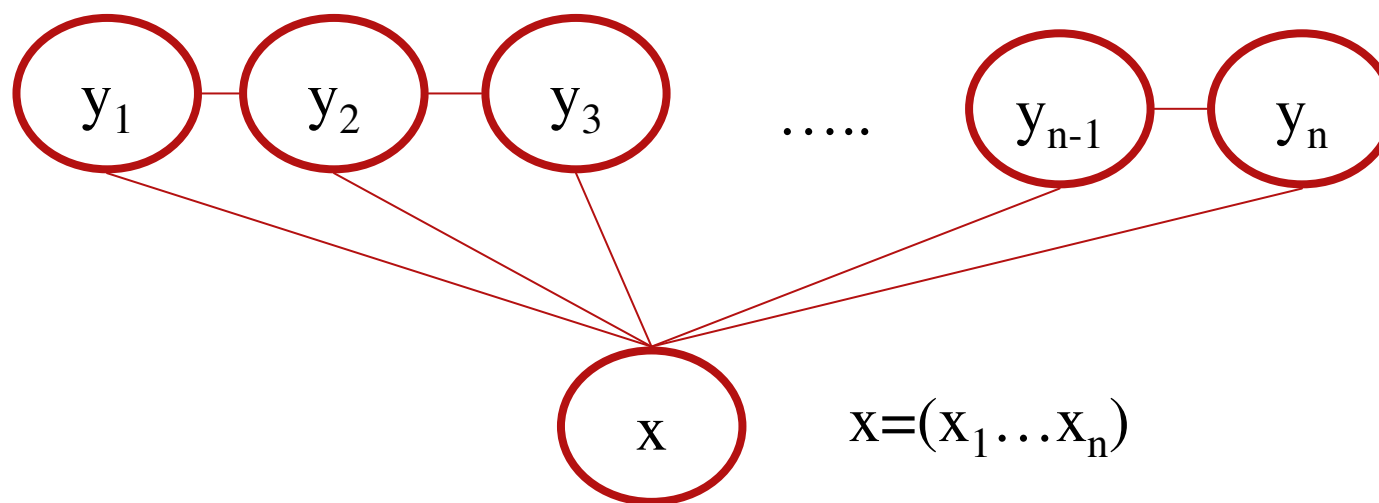




# Definition

Maximum random field  
where each random variable  $y_i$   
is conditioned on the complete input  
sequence  $x_1, \dots, x_n$

$$y = (y_1 \dots y_n)$$





# Distribution

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Distribution

$$p(y | x) = \frac{1}{Z(x)} e^{-\sum_{i=1}^n \sum_{j=1}^N \lambda_j f_j(y_{i-1}, y_i, x, i)}$$

$\lambda_j$  : parameters to be trained

$f_j(y_{i-1}, y_i, x, i)$  : feature function  
(see maximum entropy models)



# Example feature functions

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Modeling transitions

$$f_1(y_{i-1}, y_i, x, i) = \begin{cases} 1 & \text{if } y_{i-1} = IN \text{ and } y_i = NNP \\ 0 & \text{else} \end{cases}$$

Modeling emissions

$$f_2(y_{i-1}, y_i, x, i) = \begin{cases} 1 & \text{if } y_i = NNP \text{ and } x_i = September \\ 0 & \text{else} \end{cases}$$



# Training

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- Like in maximum entropy models

Generalized iterative scaling

- Convergence:

$p(y|x)$  is a convex function

↳ unique maximum

Convergence is slow

Improved algorithms exist



# Decoding: Auxiliary Matrix

Define additional start symbol

$$y_0 = \text{START}$$

and stop symbol

$$y_{n+1} = \text{STOP}$$

Define matrix  $M^i(x)$

such that

$$\left[ M^i(x) \right]_{y_{i-1}y_i} = M^i_{y_{i-1}y_i}(x) = e^{-\sum_{j=1}^N \lambda_j f_j(y_{i-1}, y_i, x, i)}$$



# Reformulate Probability

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With that definition we have

$$p(y | x) = \frac{1}{Z(x)} \prod_{i=1}^{n+1} M_{y_{i-1}y_i}^i(x)$$

with

$$Z(x) = \sum_{y_1} \sum_{y_2} \sum_{y_3} \dots \sum_{y_n} M_{y_0y_1}^1(x) M_{y_1y_2}^2(x) \dots M_{y_ny_{n+1}}^{n+1}(x)$$



# Use Matrix Properties

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Use matrix product

$$\left[ M^1(x) M^2(x) \right]_{y_0 y_2} = \sum_{y_1} M^1_{y_0 y_1}(x) M^2_{y_1 y_2}(x)$$

with

$$Z(x) = \left[ M^1(x) M^2(x) \dots M^{n+1}(x) \right]_{y_0=START, y_{n+1}=STOP}$$



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Software





# CRF++



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- See <http://crfpp.sourceforge.net/>



# Summary

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- Sequence labeling problems
- CRFs are
  - flexible
  - Expensive to train
  - Fast to decode