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**Re: Evaluation of SAMS – control software**

We would like to confirm you that SAMS software, the software for computing velocity-dependent safety zone for autonomous mobile robots, has been developed according to the software development process as laid out in IEC 61508-3:2008 (SIL 3).

The related analyses and tests have shown that there are no safety related objections against the use of SAMS software for the computation of velocity dependent safety zone.

Yours sincerely

TÜV SÜD Rail GmbH  
Rail Automation

  
i.V. Günter Greil  
Technical Certifier

  
i.A. Dr. Peerasan Supavatanakul  
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