

# Hardware-Setups for Interactive Stereoscopic Surfaces

ISIS3D Tutorial @ ITS 2013, St Andrews

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# 3D User Interface Visions



Nathan Shedroff and Christopher Noessel. *Make it So: Interface Design Lessons from Sci-Fi*. Rosenfeld Media, September 2012.

# Scifi Vision



IronMan, 2008

# CAD Sellers Vision



# CAD Sellers Vision



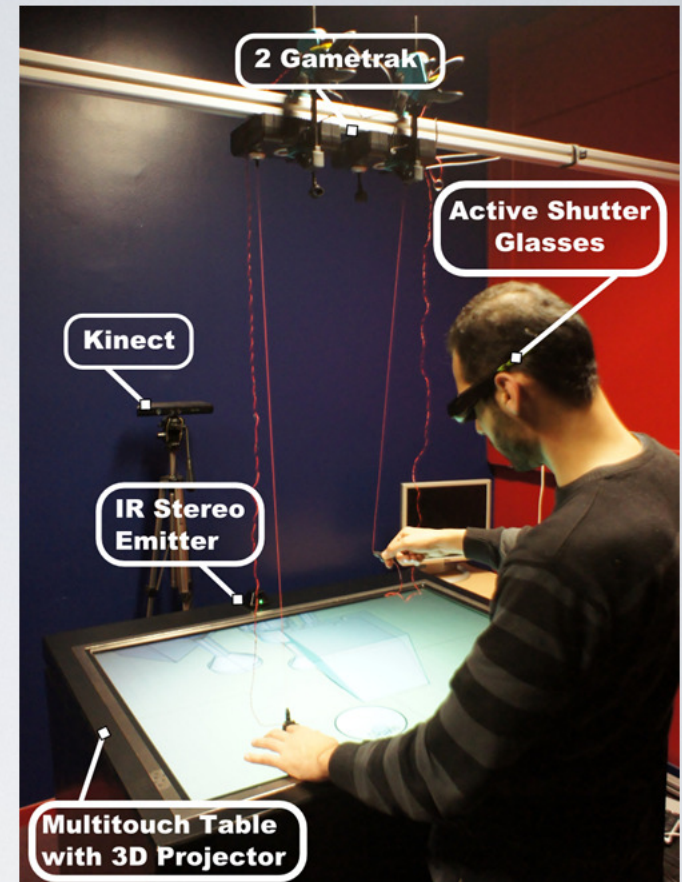
See what you mean Dassault 2005 , 2007

# Outline

- Overview
- 2D Input MT
- Output 3D
- 3D Inputs
- Putting It All Together

Hardware-Setups for Interactive Stereoscopic Surfaces

# STEREOSCOPIC SURFACES OVERVIEW



# Commercial Solutions



Perceptive Pixel 55"



ZSpaceSystem 24"



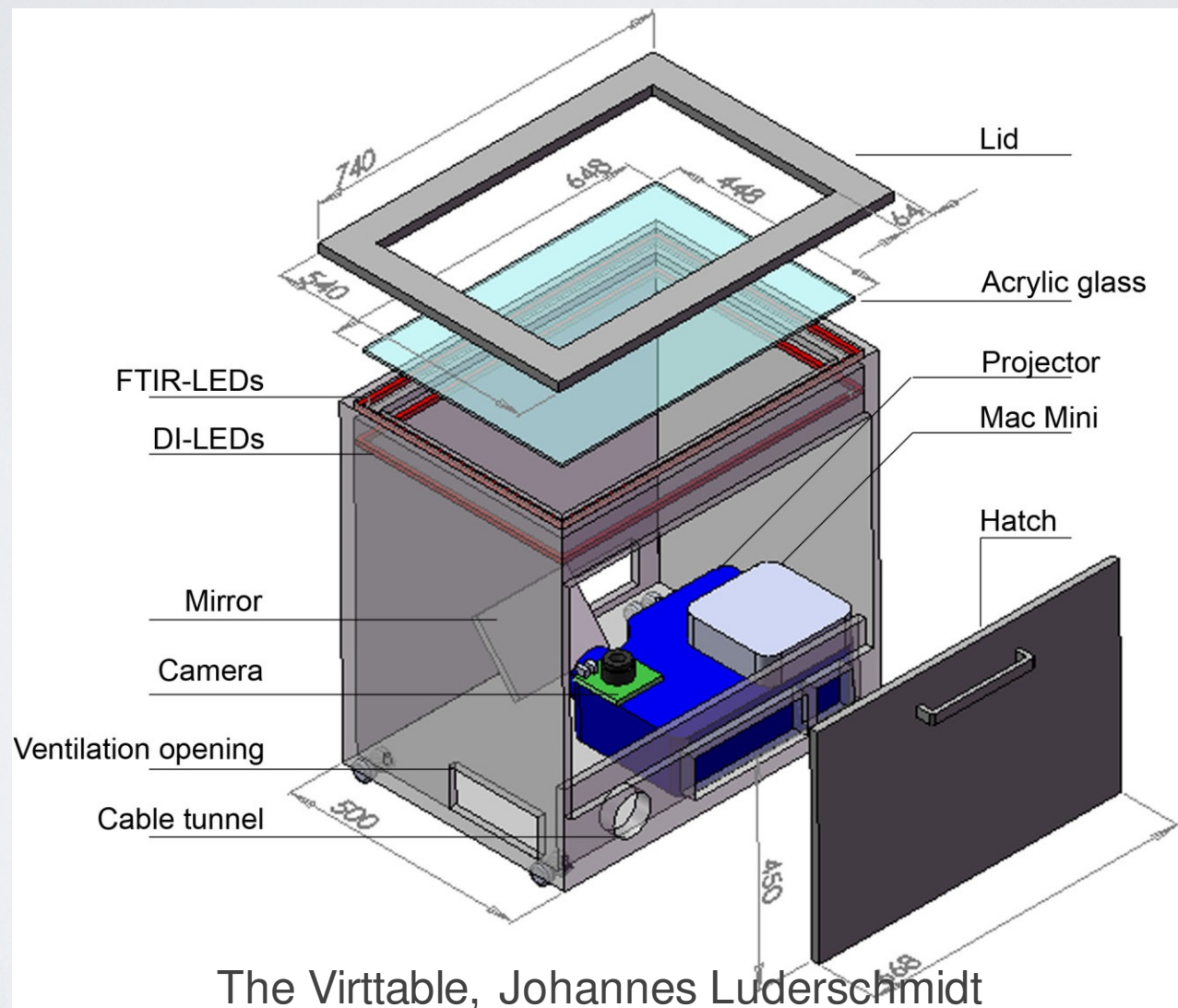
© Immersion Immersion



Immersion iliGHT 3D-Touch



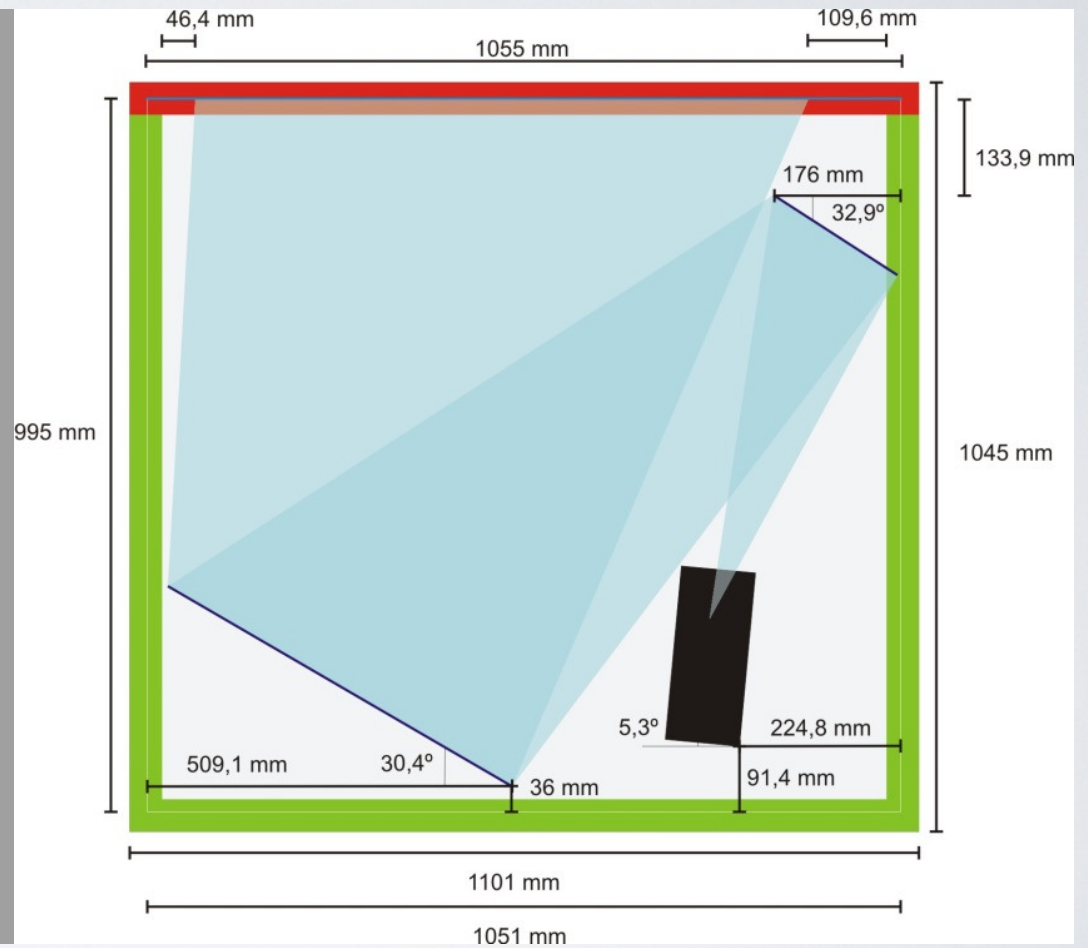
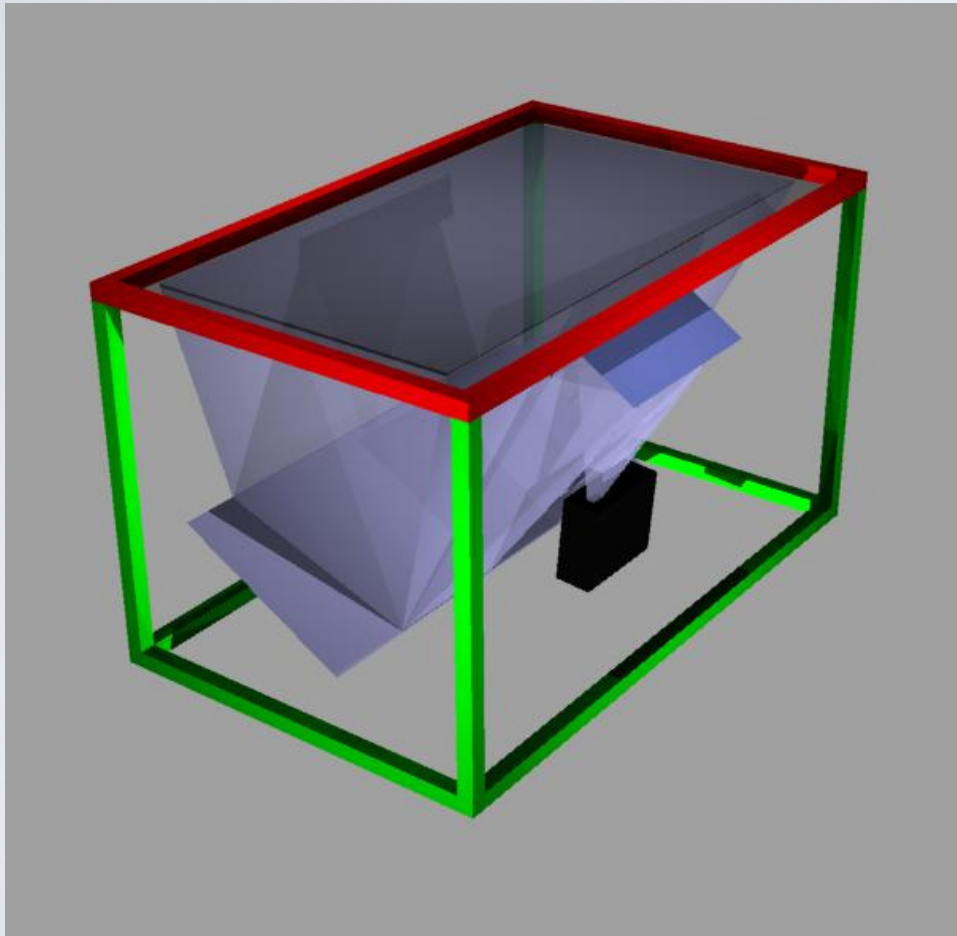
# DIY Multi-touch Table



# HW Design Choice

- 3D Vision System : TV or Projector
- Multi-touch Sensor
- 3D Tracking
- 3D Inputs
- Frame & Packaging

# Vision & Packaging



# Frame Example



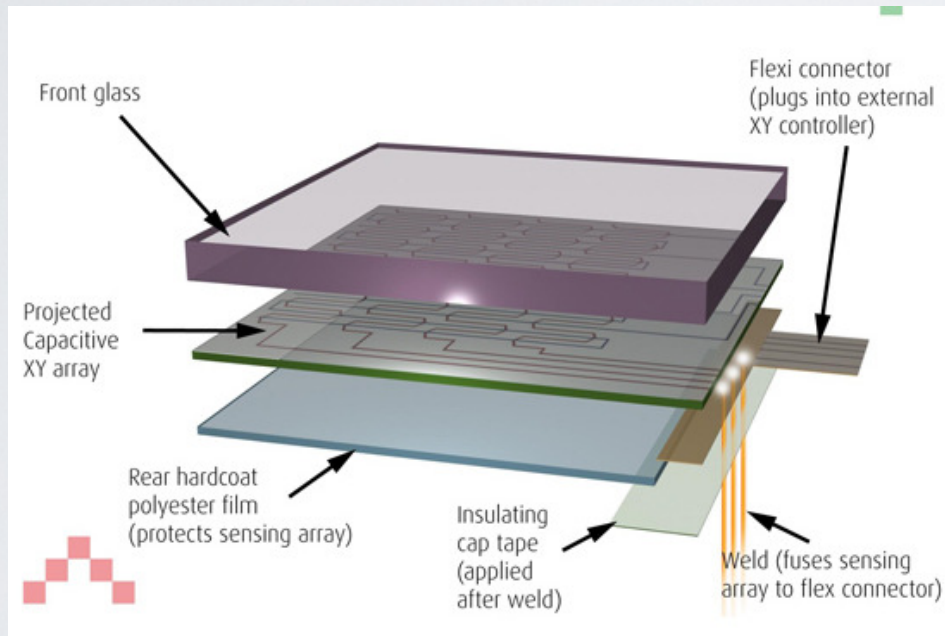


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## **INPUT: MULTI-TOUCH TECHNOLOGIES**

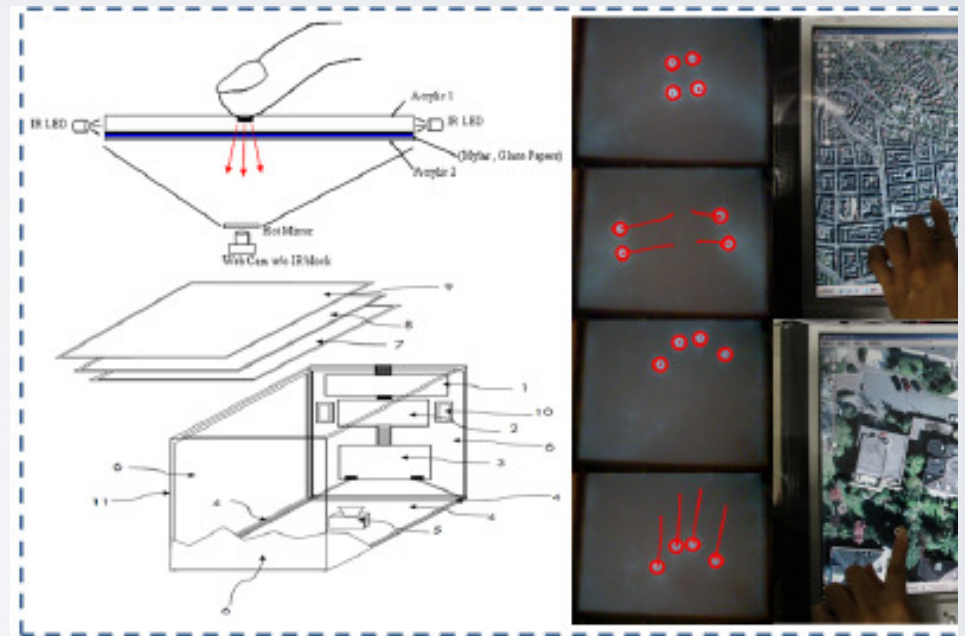
# Multi-Touch Strategies

## Sensor Based Solutions



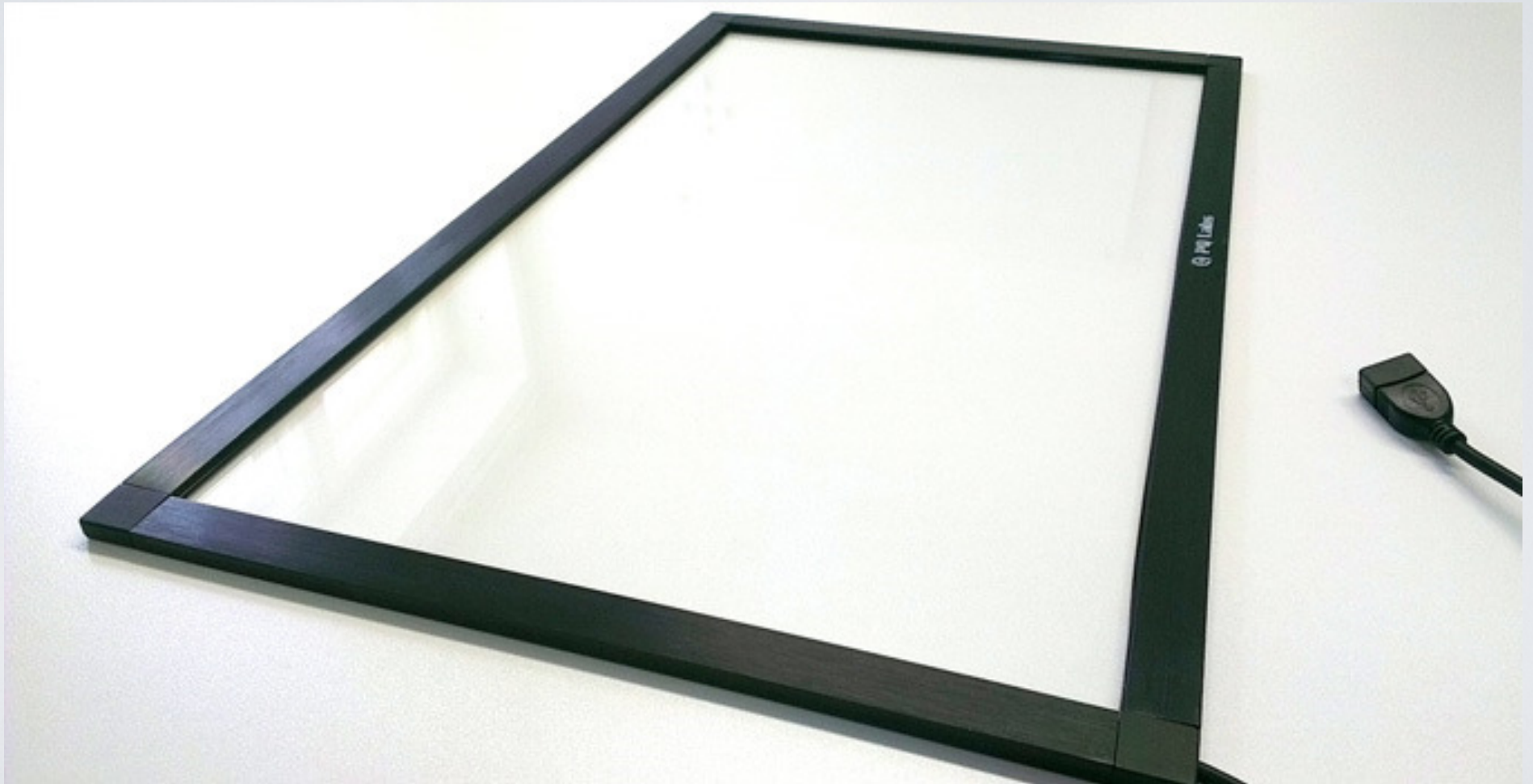
Zytronic PCT

## Vision Based Solutions



Chen et al., Vision-Based Finger Detection, Tracking, and Event Identification Techniques for Multi-Touch Sensing and Display Systems, Sensors, 2011

# IR Based Touch Frame Overlays



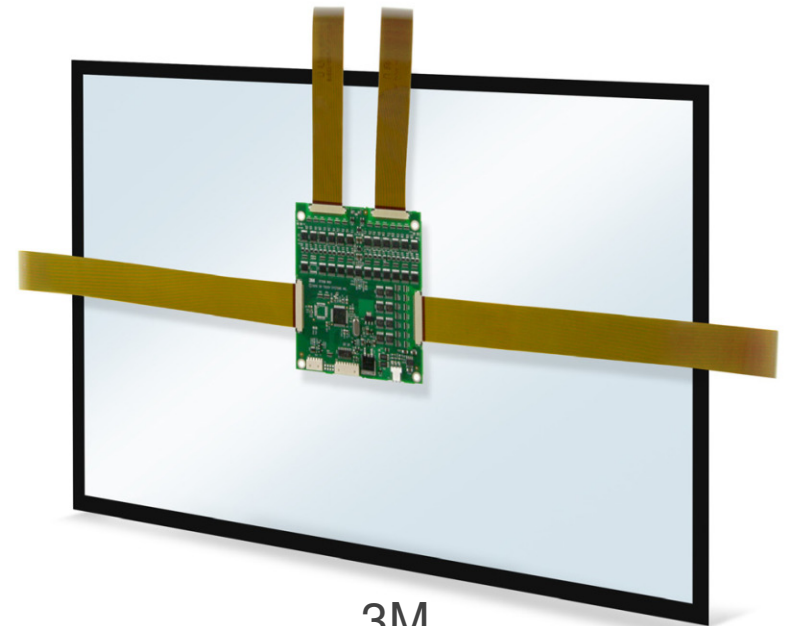
Examples: PQ Labs, ZaagTech

# Projected Capacitive Touch



Displax

Film



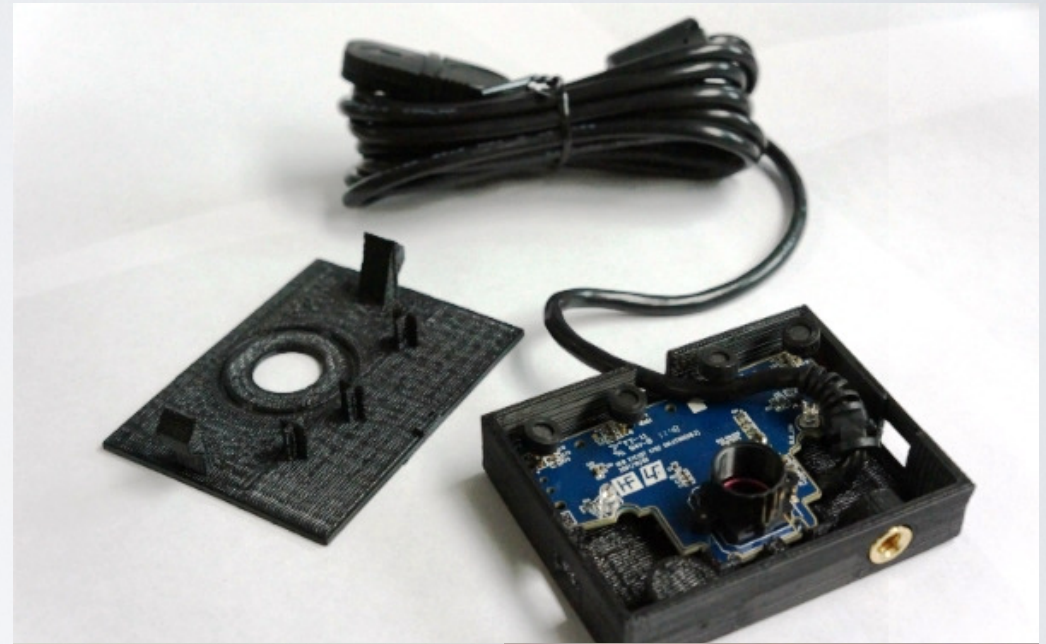
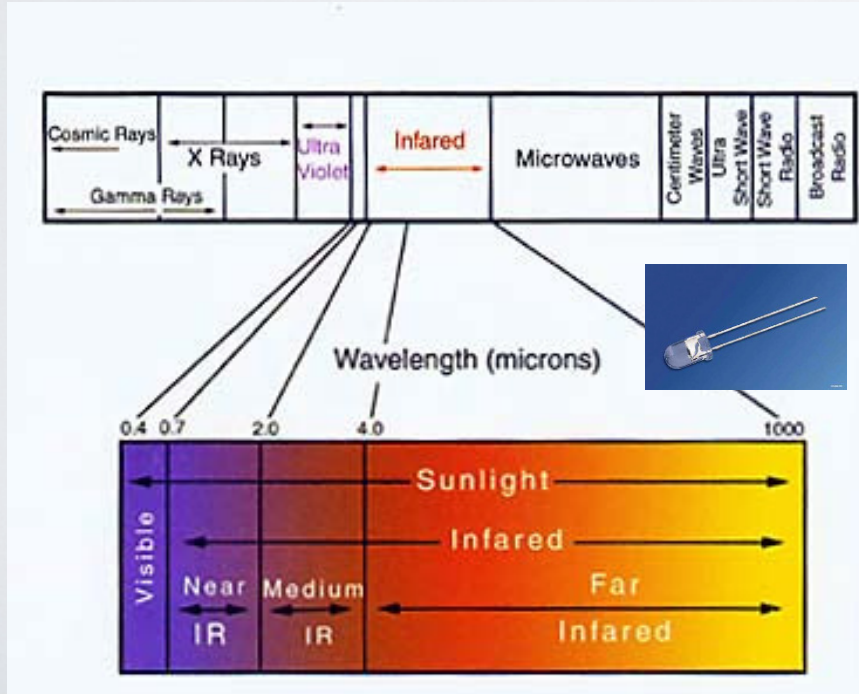
3M

Complete Frame



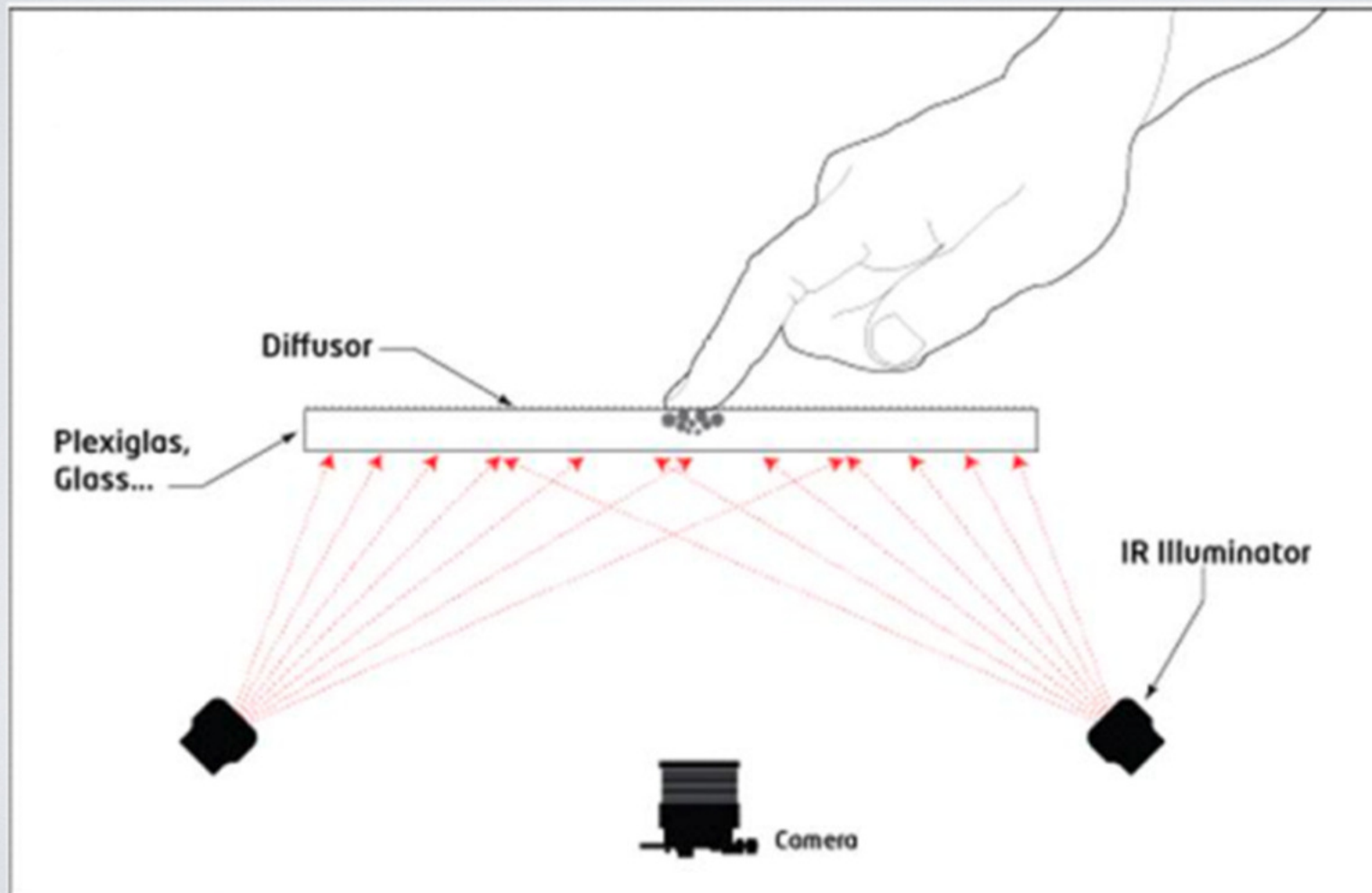
# Vision Based Multi-touch

- Near Infrared Light  
MT : 750 – 940 nm  
Common : 780 – 880 nm



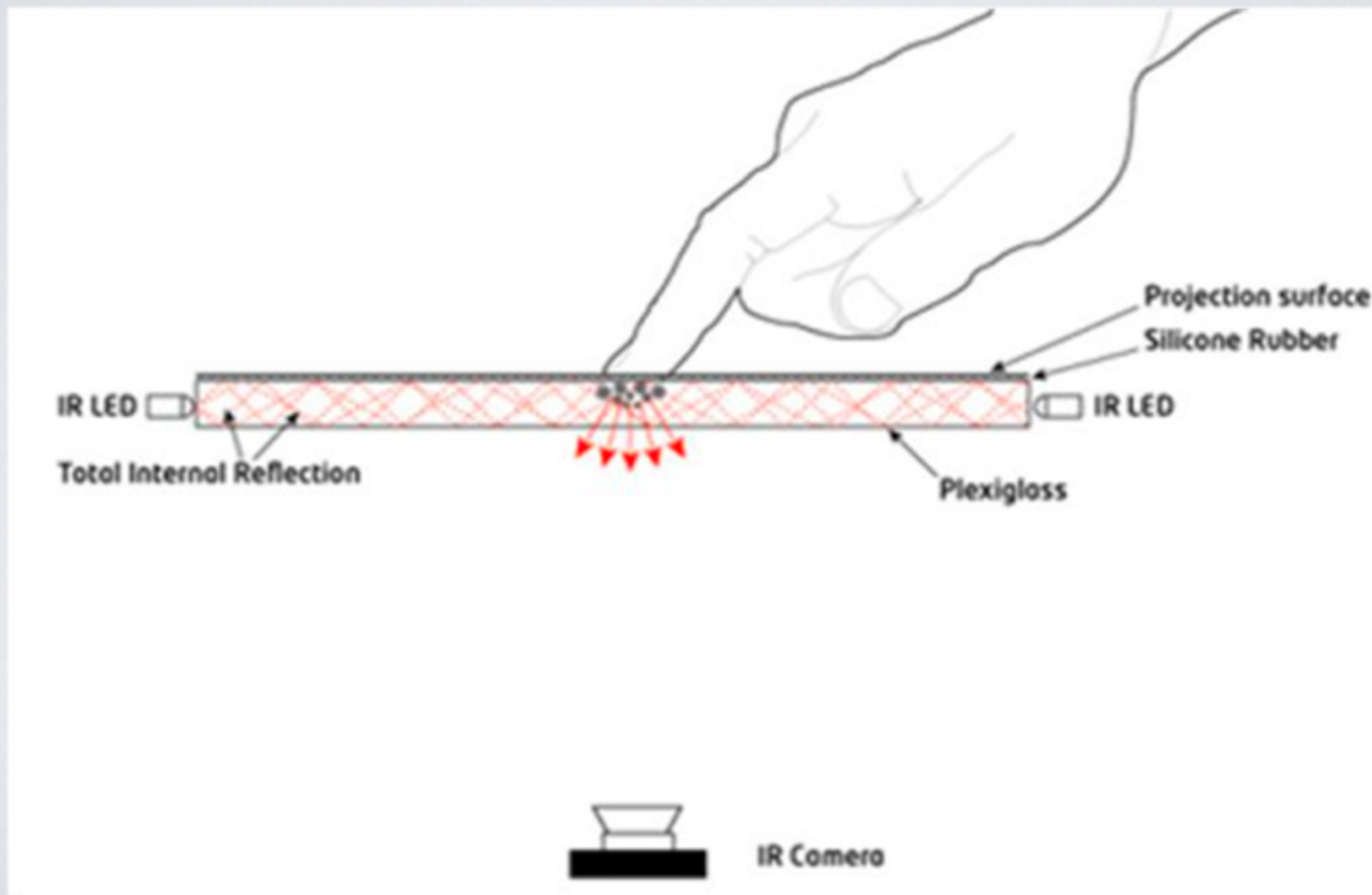
# Multi-touch Input Technology

- (Rear) Diffused Illumination DI



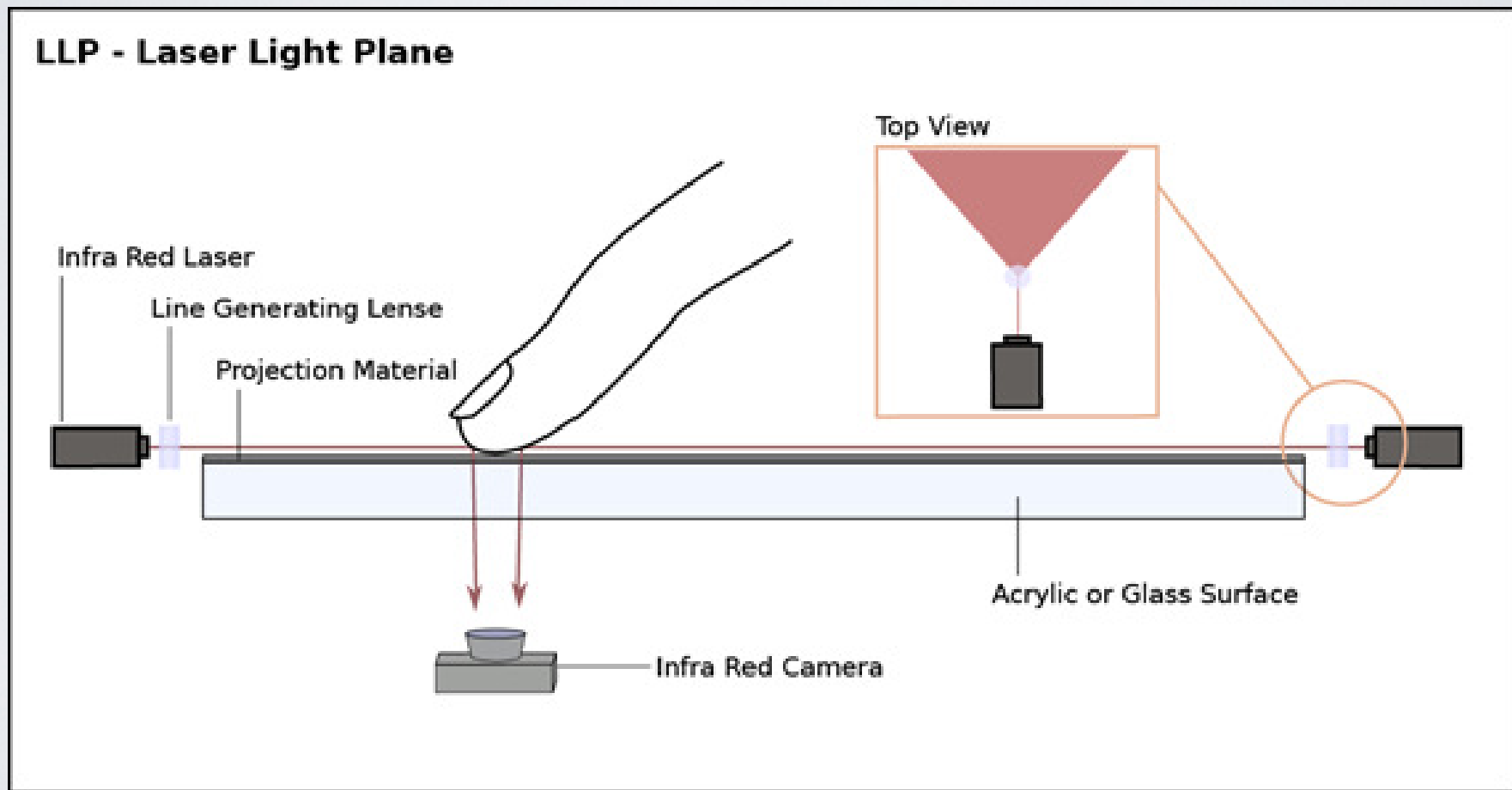
# Multi-touch Input Technology

- Frustrated Total Internal Reflection FTIR

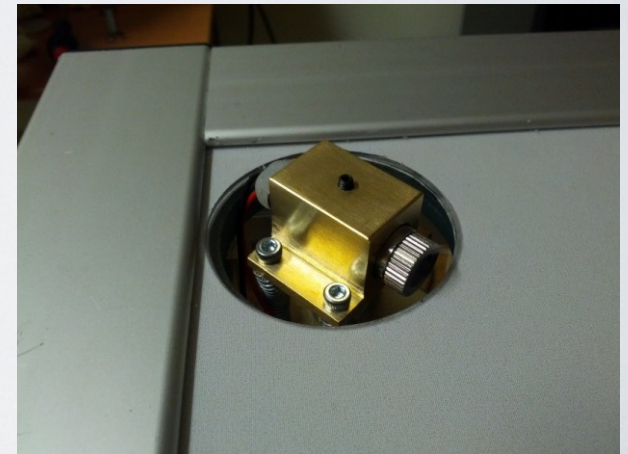
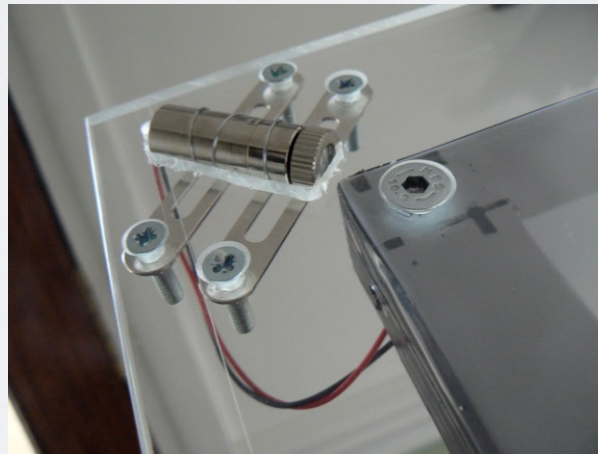
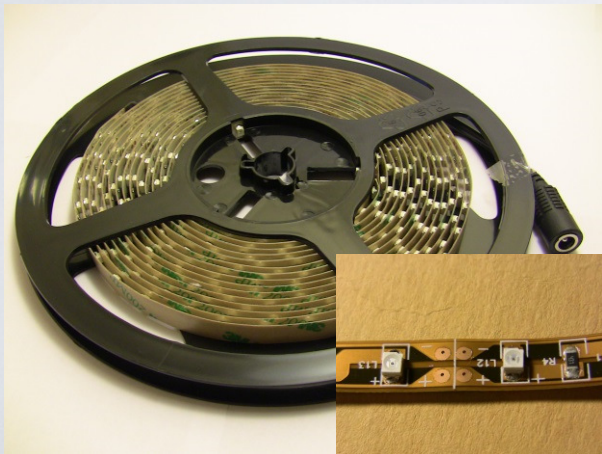


# Multi-touch Input Technology

- Laser Light Plane LLP

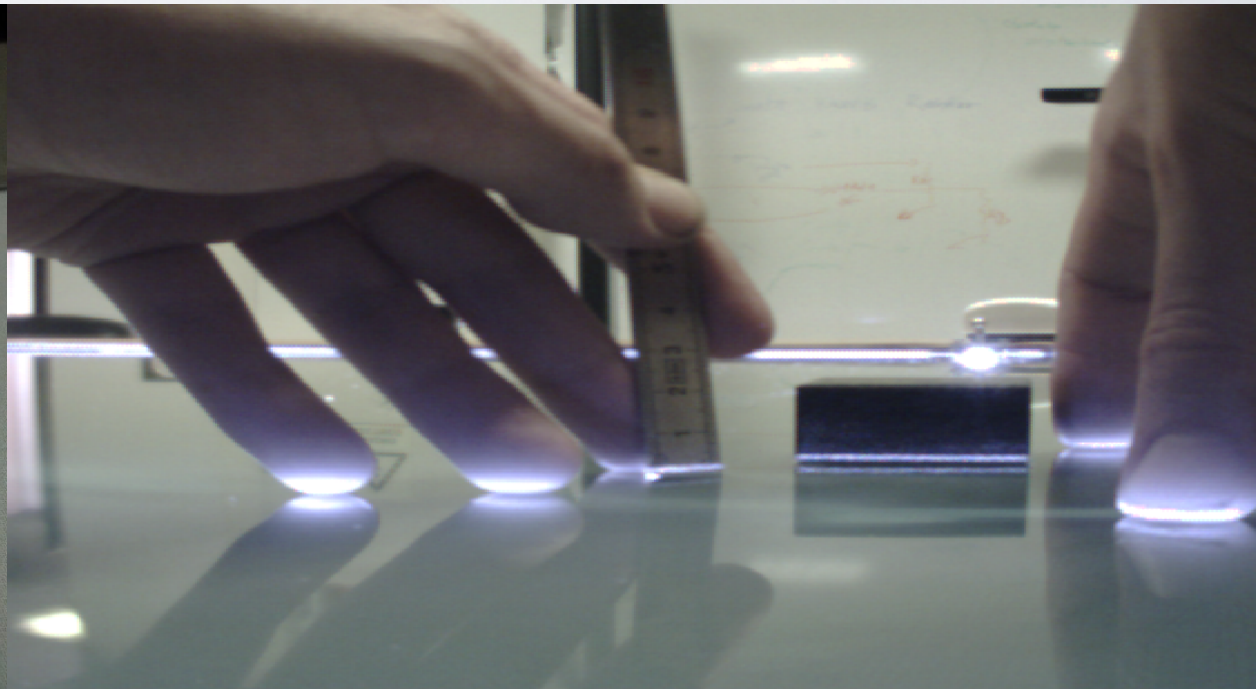


# Infrared Light Solutions



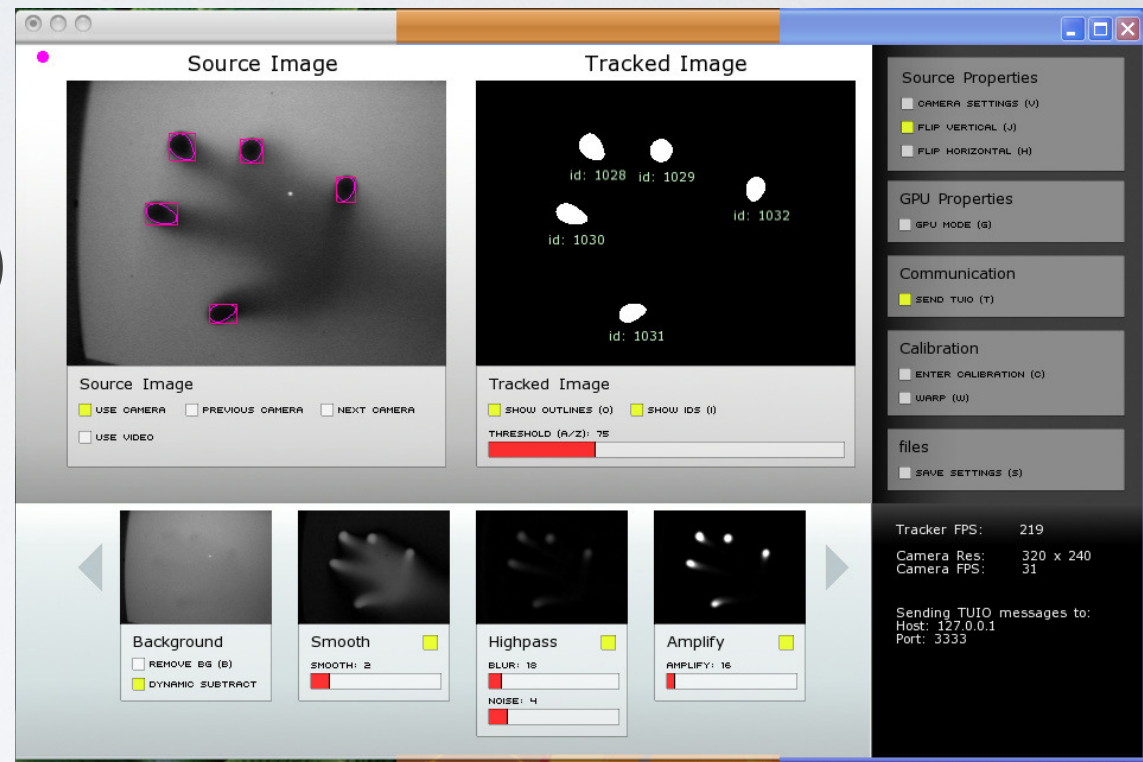
<http://peaproductions.com>

# LLP Surface Example



# MT Software

- OS Recognized Touches (WM\_TOUCH)
- Proprietary API
- USB/HID
- Vision Based Software



NUIGroup.com

# TUIO Protocol

- Open Source Spec.
  - <http://tuio.org/>
- OSC
- UDP / TCP (3333)
- Multi Device
- Multi Platform
- 2D , 3D, Tangibles

## 2D Interactive Surface

/tuio/2Dobj set s i x y a X Y A m r

/tuio/2Dcur set s x y X Y m

/tuio/2Dblob set s x y a w h f X Y A m r

## 2.5D Interactive Surface

/tuio/25Dobj set s i x y z a X Y Z A m r

/tuio/25Dcur set s x y z X Y Z m

/tuio/25Dblob set s x y z a w h f X Y Z A m r

## 3D Interactive Surface/

tuio/3Dobj set s i x y z a b c X Y Z A B C m r

/tuio/3Dcur set s x y z X Y Z m

/tuio/3Dblob set s x y z a b c w h d v X Y Z A B C m r

## custom profile

/tuio/\_[formatString]

/tuio/\_sixyP set s i x y 0.57





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# **OUTPUT: 3D TECHNOLOGIES**

# 3D Projectors & TVs

- High Res => Low Brightness
- 120 Hz Sequential
- HDMI 1.4a
- Short-Throw , Mirrors



Optoma GT750

# Output 3D

- Stereo Capabilities
- Graphic Cards
- Glasses + Emitters

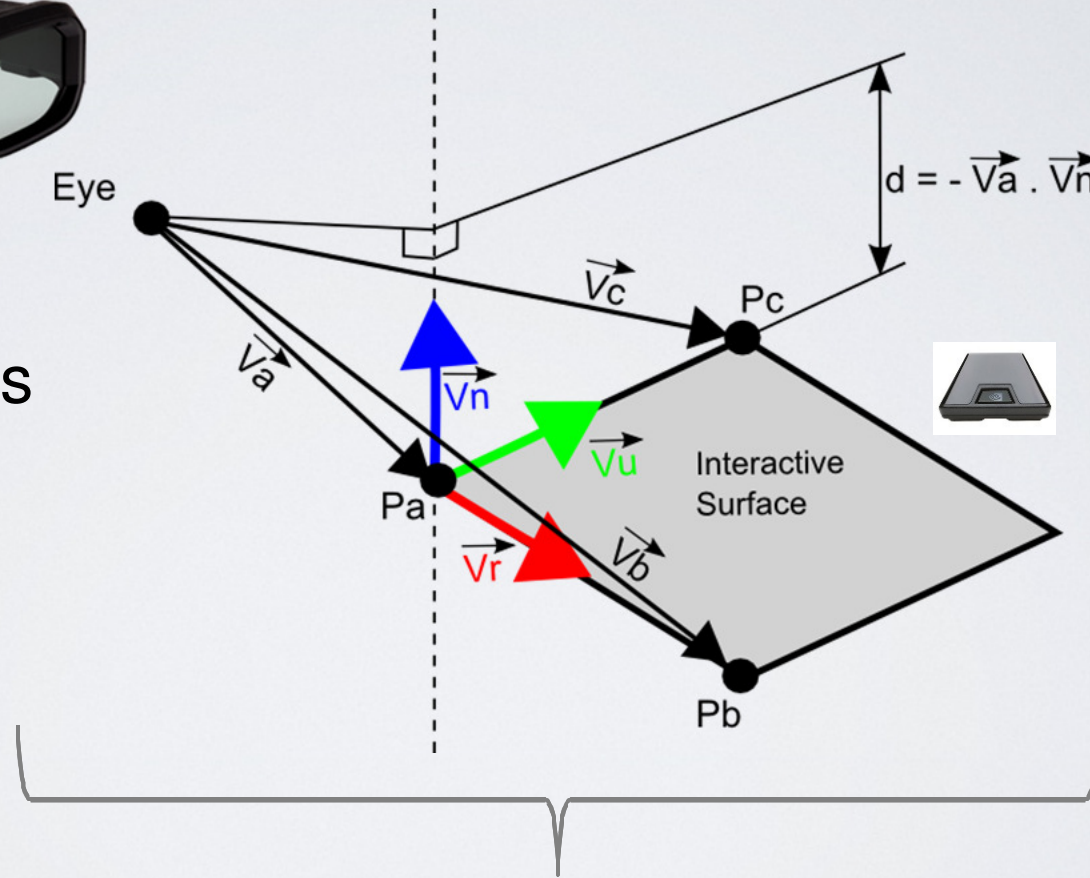


Nvidia Quadro and Vision

# 3D Visualization



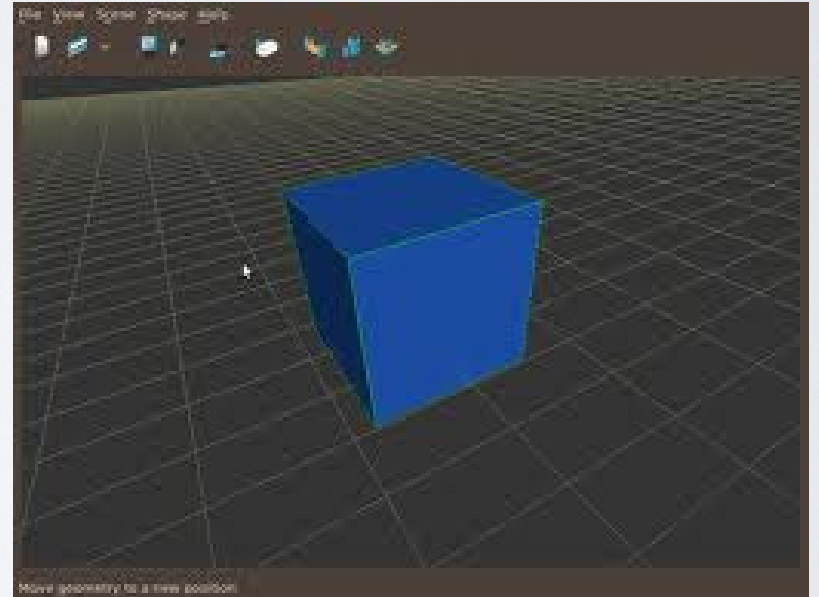
120 Hz  
Shutter Glasses



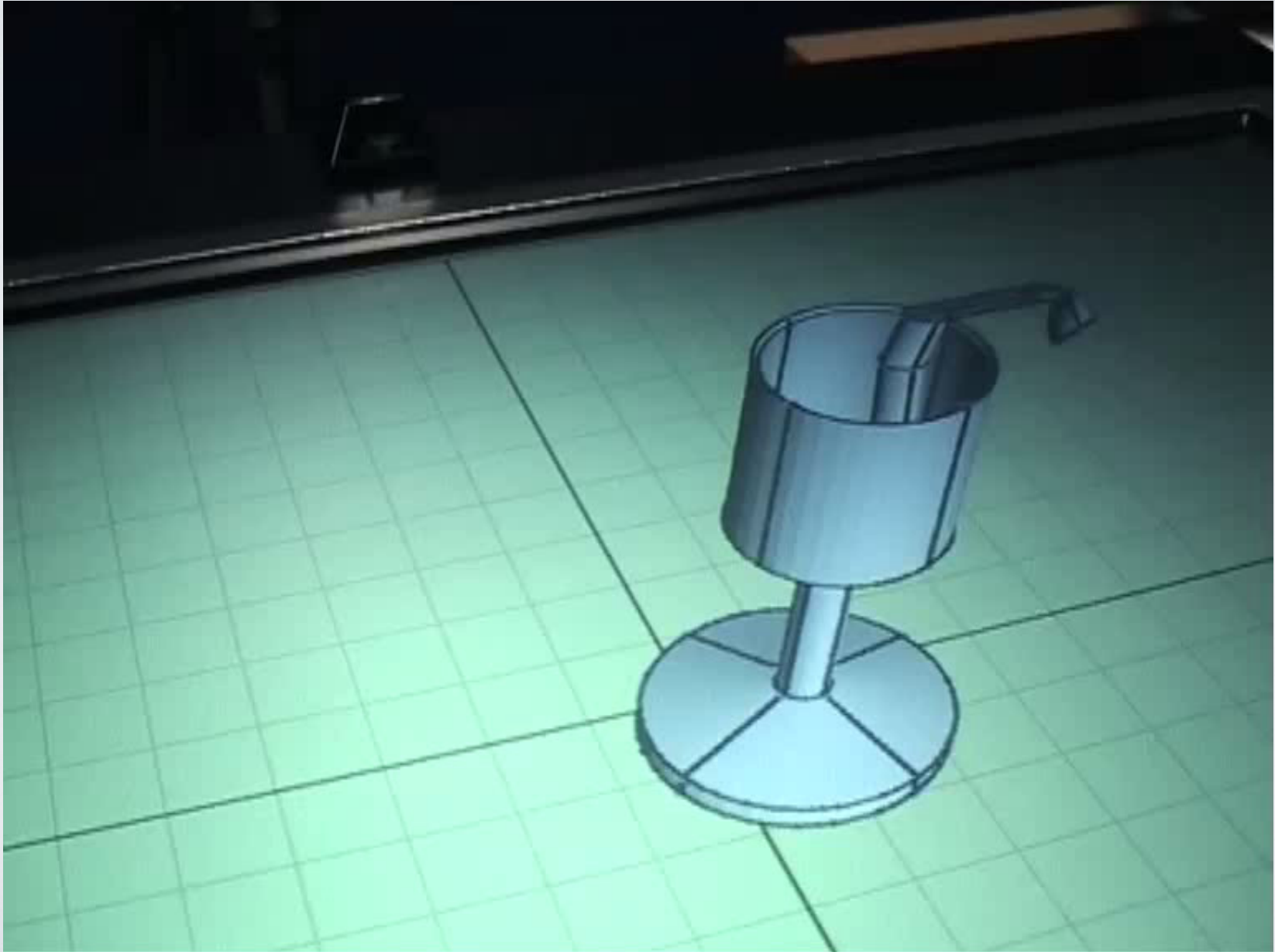
x2 Per each eye (Interpupillary Distance 6 cm)

# Rendering Solutions

- Render Engine or Frameworks
  - OpenGL, OpenSG
  - Cinder, Kiwy
  - Unity + MiddleVR,
  - Blender, Unreal , G3D



# 3D Visualization

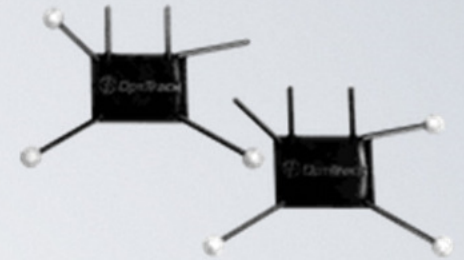
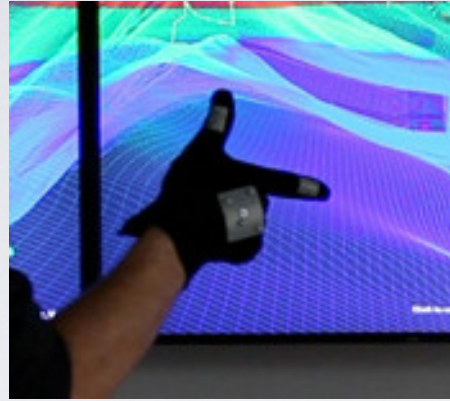
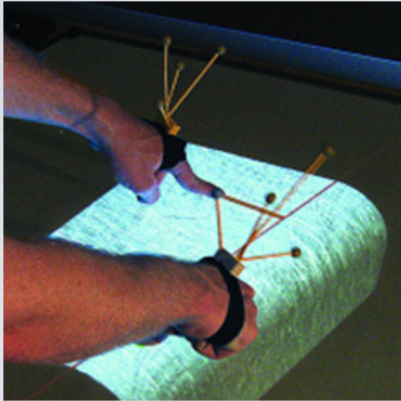




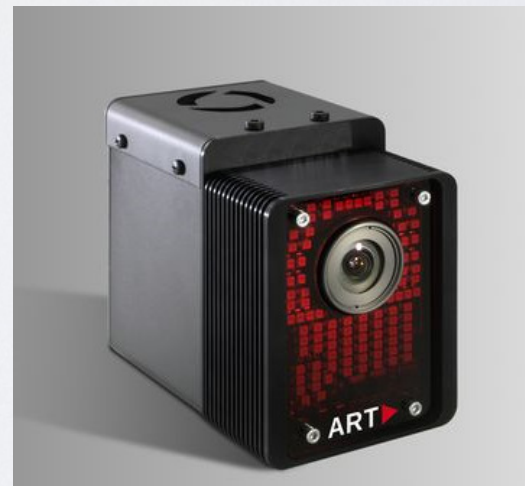
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## **INPUT: 3D TECHNOLOGIES**

# Optical Tracking



- Very Accurate
- 100 to 400 Hz
- VRPN
- Intrusive & Expensive

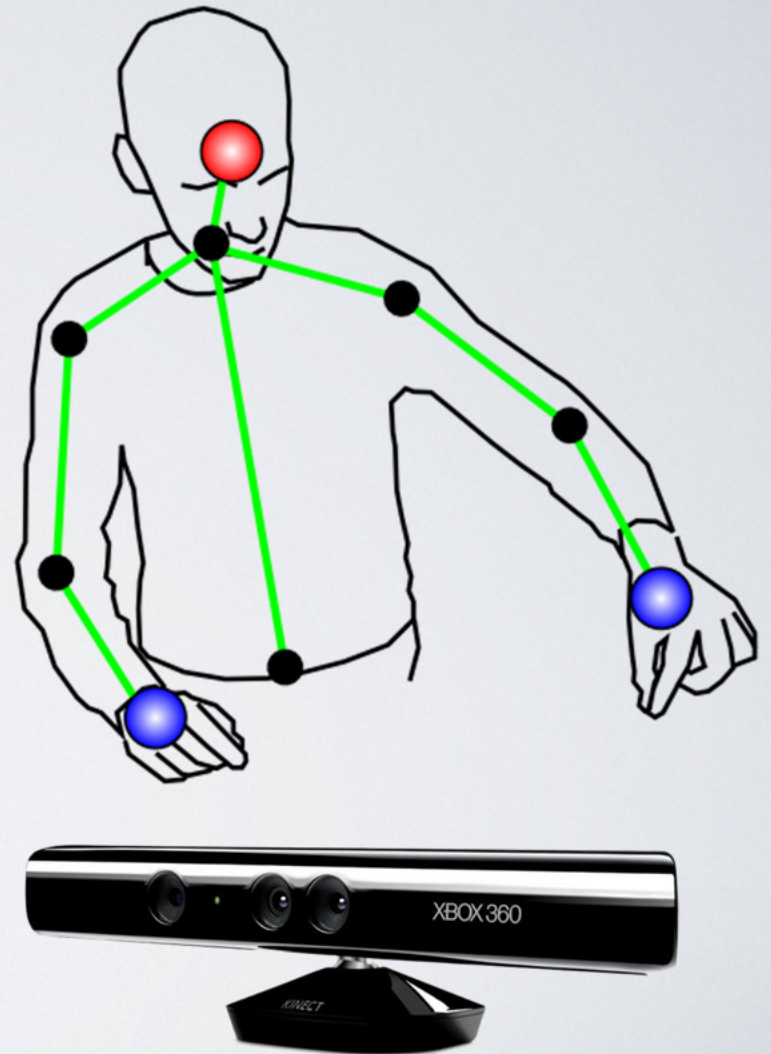




# Body Tracking

## KINECT

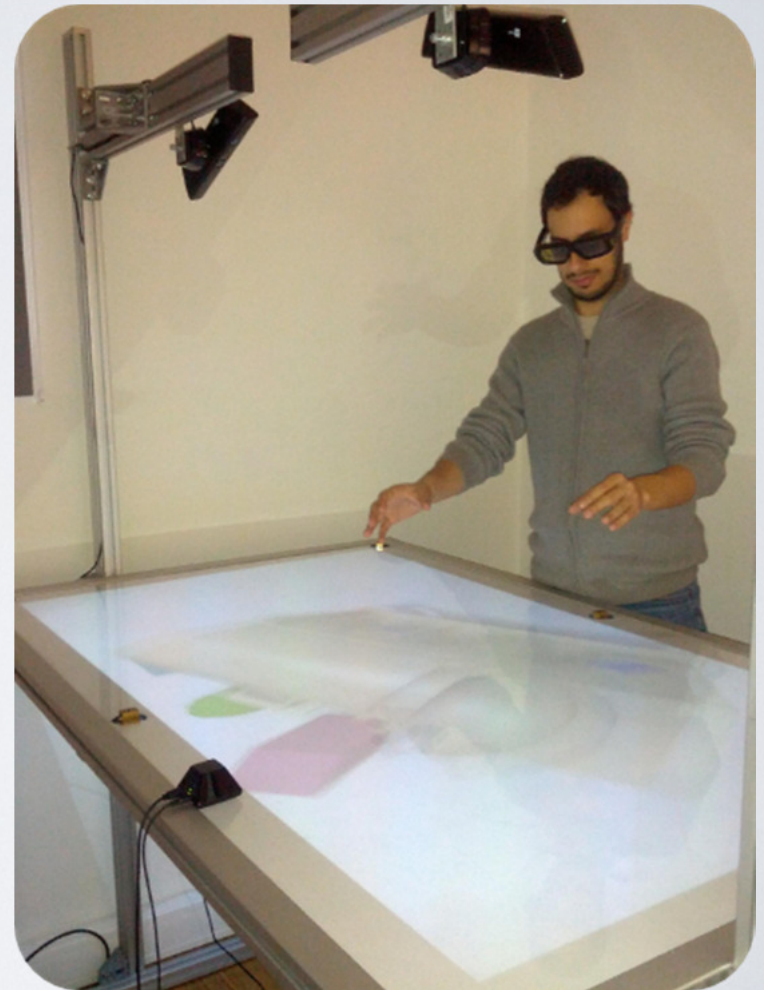
- Skeleton Tracking
- Pose Recognition
- 6 DOF Hand + Head
- Windows SDK
- OpenNI/NITE
- 30 Hz



# Hand and Finger Tracking



- Kinect Based (1 or 2)
- Mac OS, WIN 64 bits
- 6DOF Hand Tracking
- Finger tracking
- Pose Recognition
- 30 Hz



# 3D Finger Tracking

LEAP  
M O T I O N

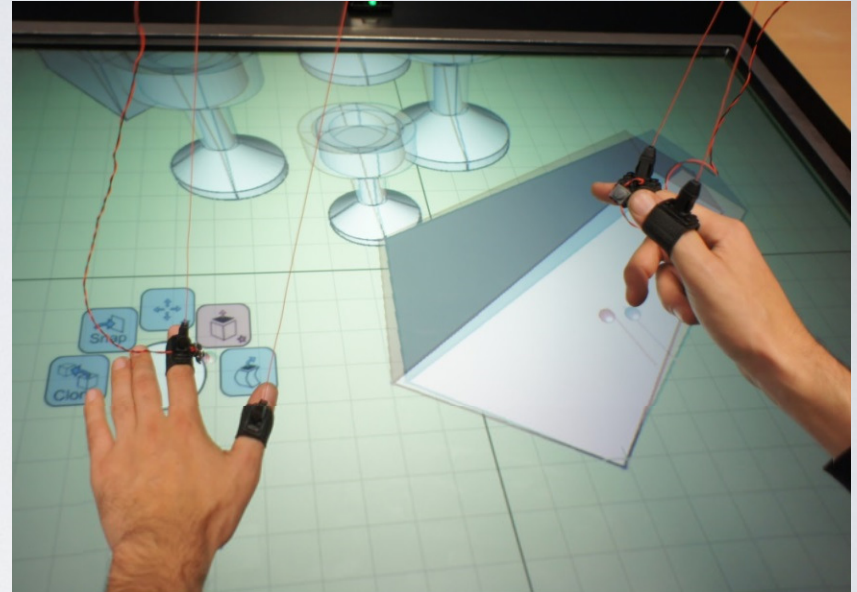
- Mac OS, WIN
- 6DOF Hand Tracking
- Finger tracking
- Gesture Recognition
- Very Limited Volume
- 30 to 200 hz



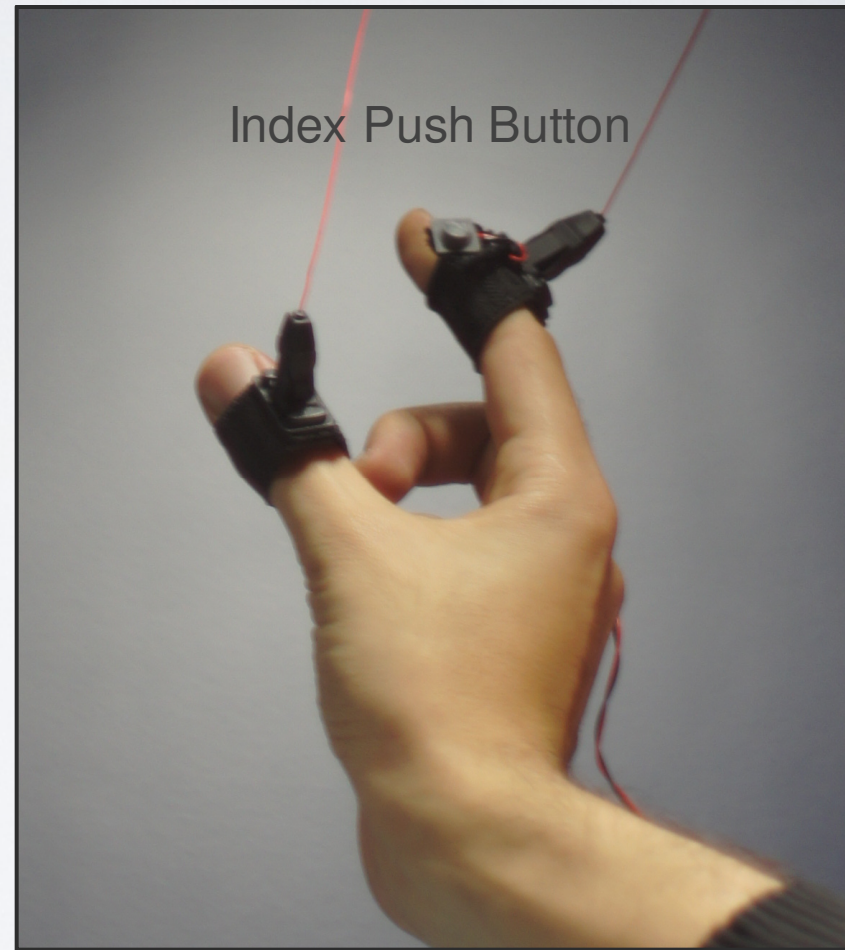
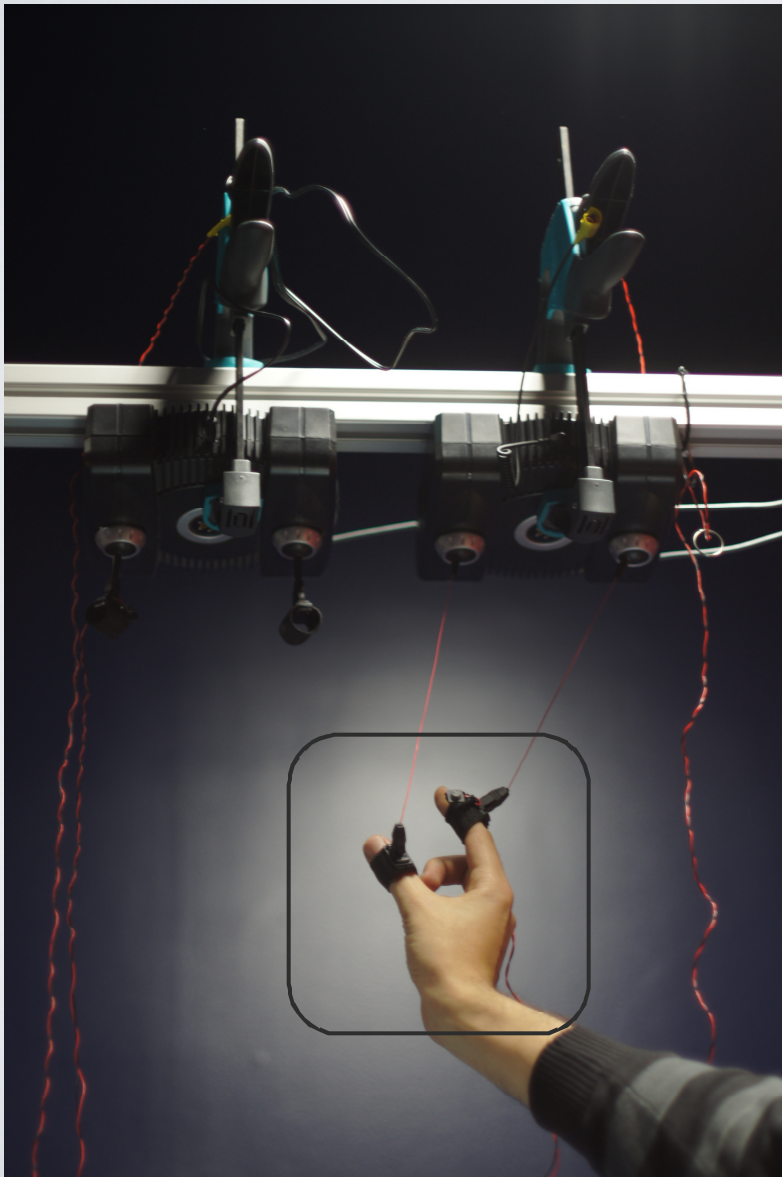
# 3D Finger Tracking



- String Length Based
- 2 x 3D Tracking
- Button input
- 100 Hz – 120 Hz
- Intrusive



# 3D Finger Tracking

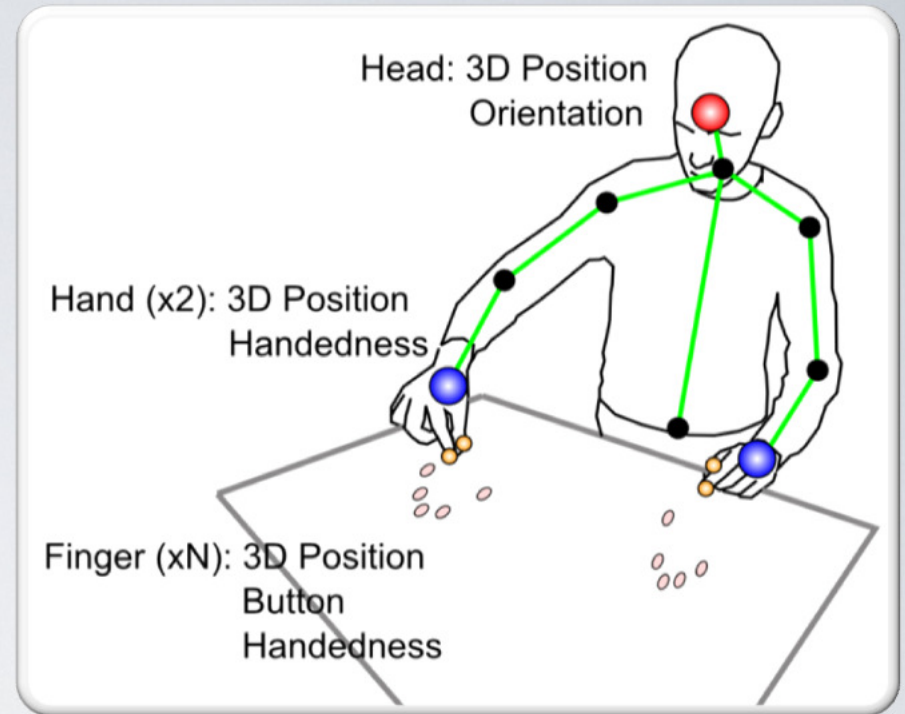


# Other Devices



# Common API and Protocols

- OpenNI / NITE
- Kinect Windows SDK
- Three Gears
- FFAST
- VRPN
- TUIO



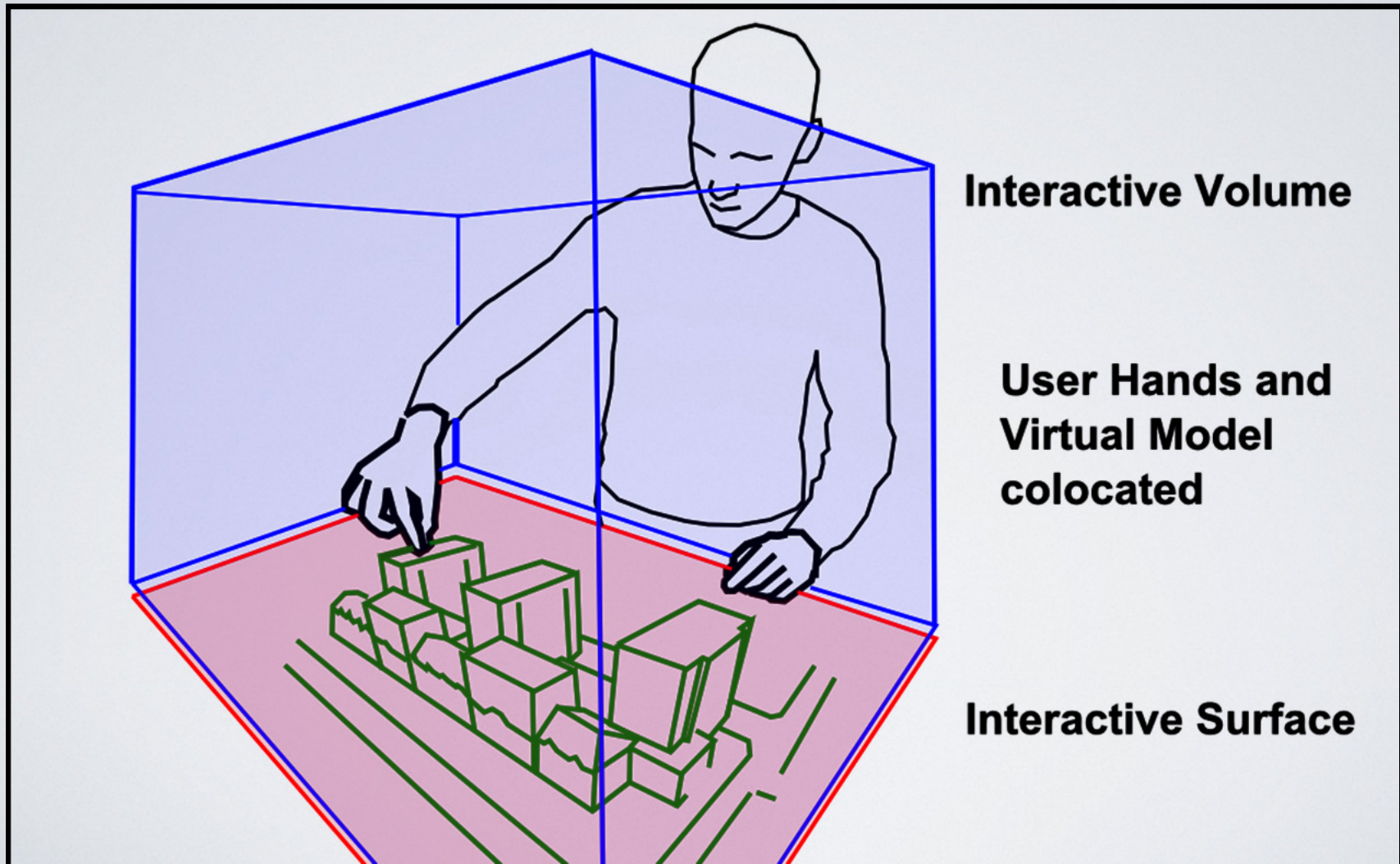
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# PUTTING ALL TOGETHER

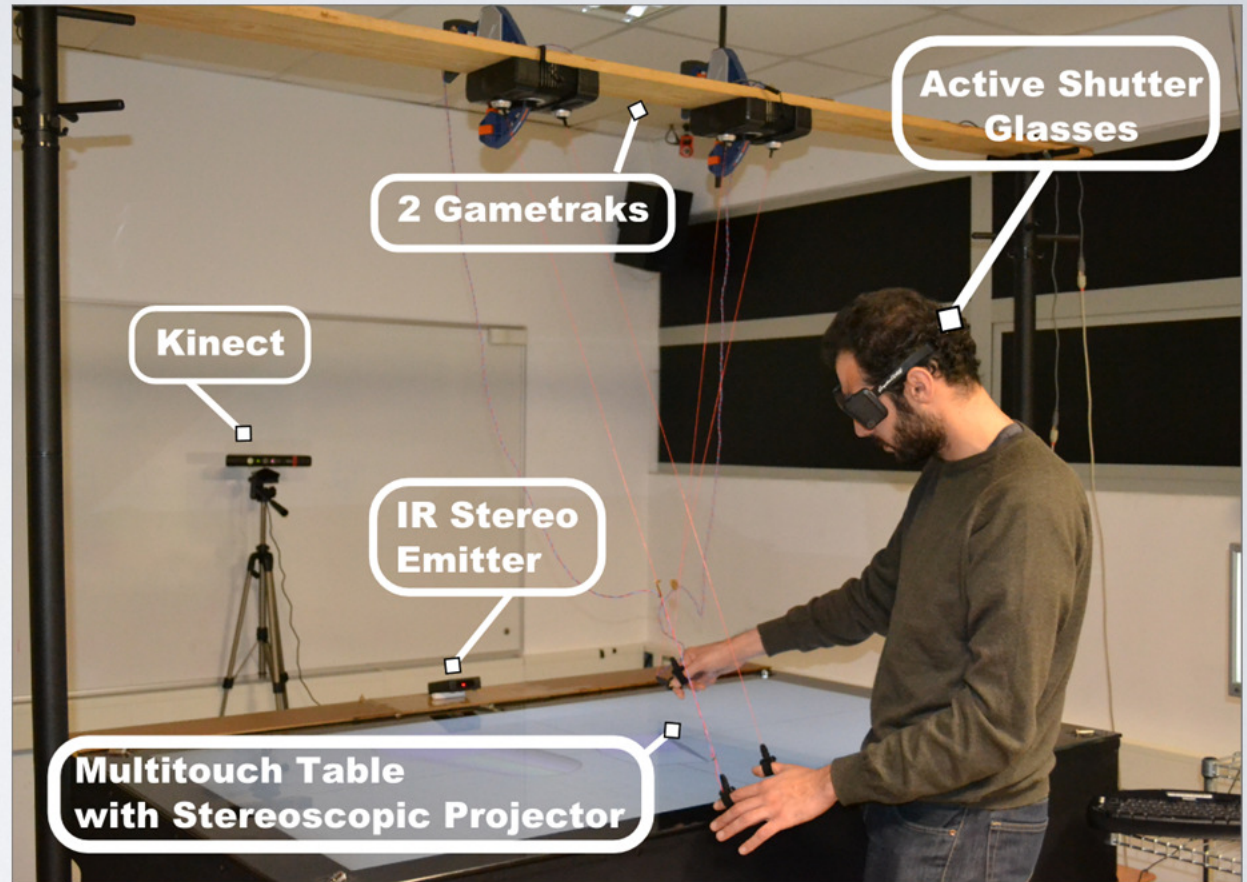
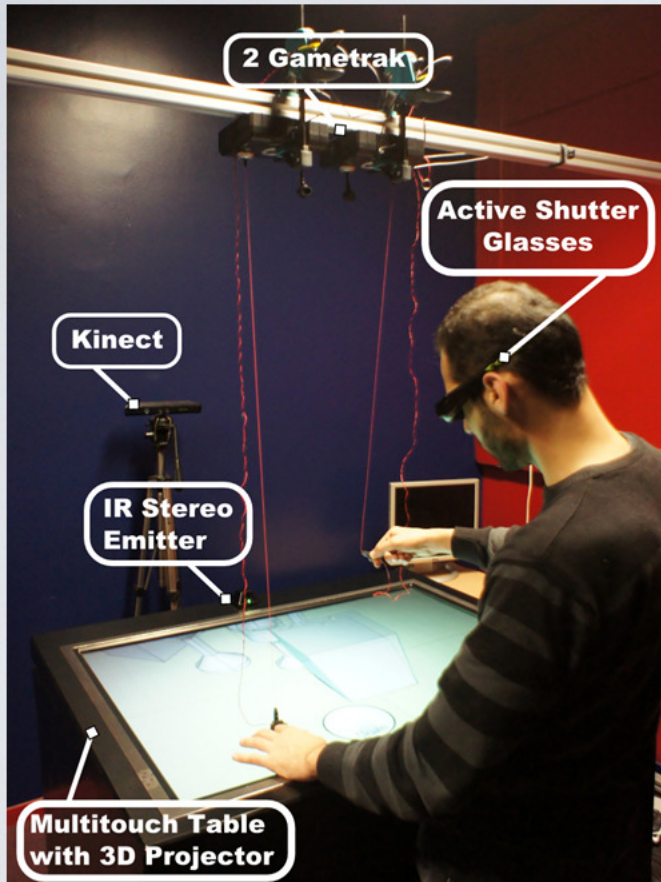
## 3D I/O TABLETOP



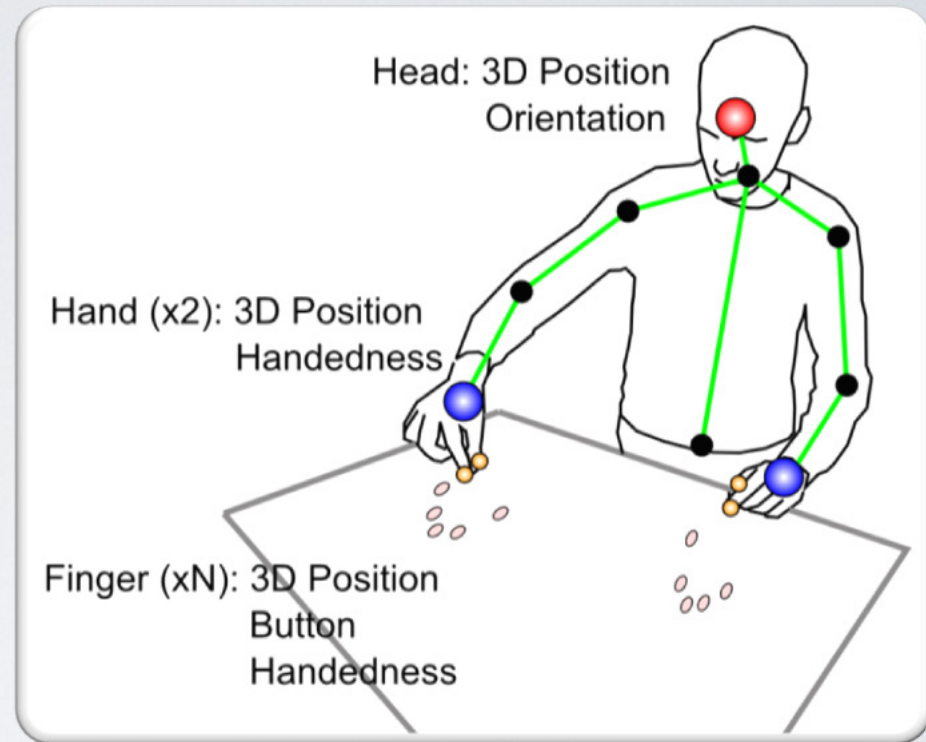
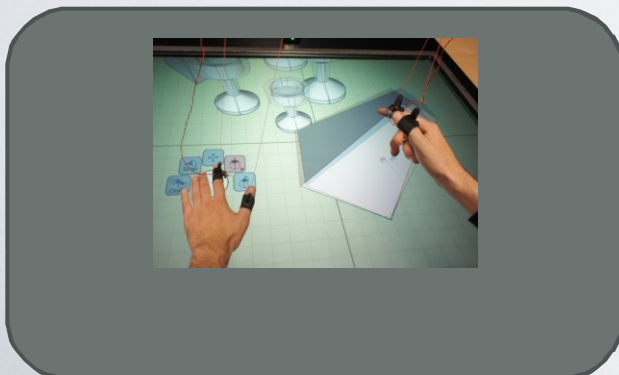
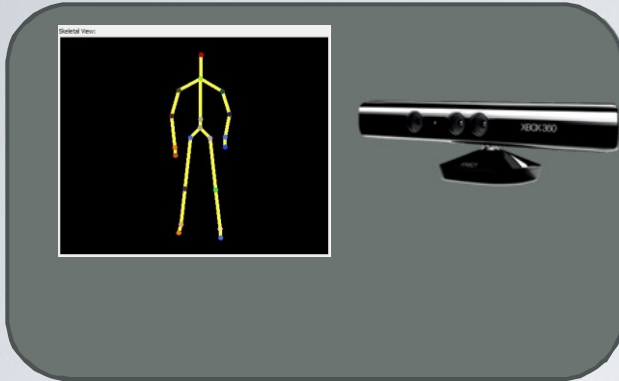
# Interaction and Visualization Spaces



# Setup Examples



# Creating a Unique User Model



Finger **X** from Hand **Y** on or above the surface from user **Z**

# Multiple Coordinate Systems

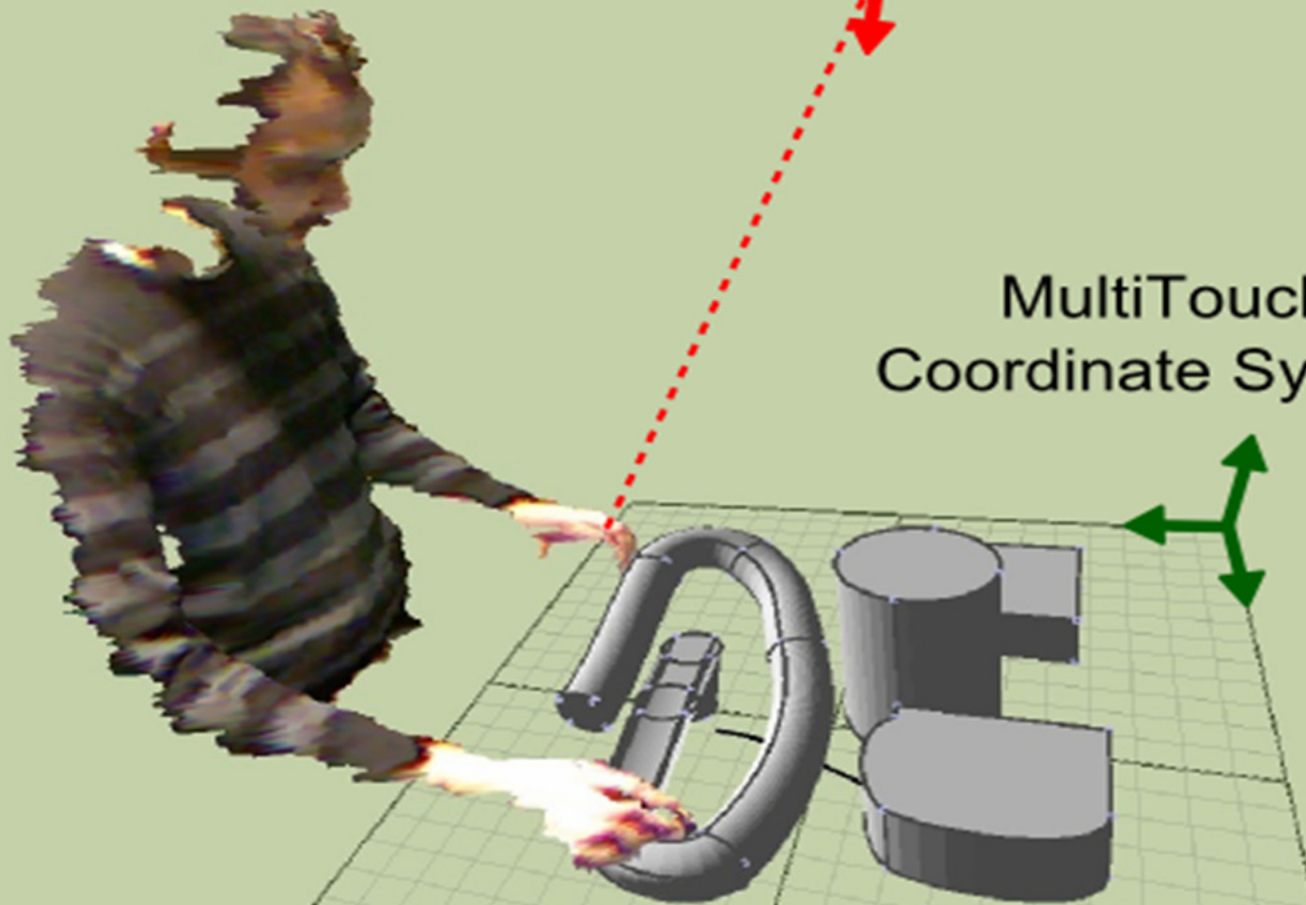
Gametrak  
Coordinate System (4x)



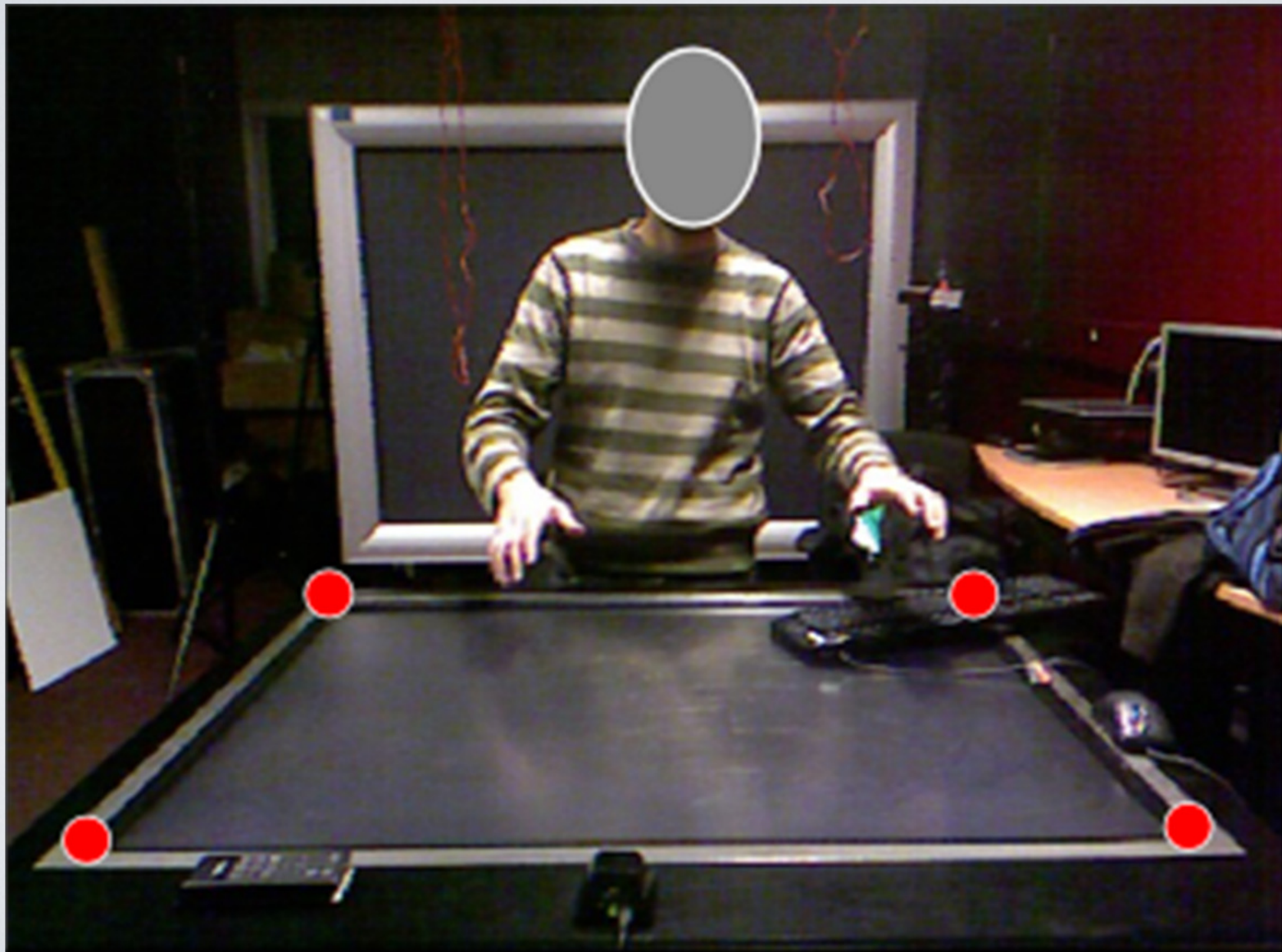
MultiTouch  
Coordinate System



Kinect  
Coordinate System



# Multi-Touch to Kinect Space



# Gametrak to Kinect Space

Surface Sampling  
Collecting 1k pairs



2D touch raw data  
3D Gametrak raw data

2D touch to 3D touch  
Conversion



3D touch data  
3D Gametrak raw data

Compute 6 DoF Rigid  
Transformation [Fischler81]



Transformation Matrix

4 x  
( 1 per string)

