

Article

HybridTabNet: Towards Better Table Detection in Scanned Document Images

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Abstract: Tables in document images are an important entity since they contain crucial information. Therefore, accurate table detection can significantly improve the information extraction from documents. In this work, we present a novel end-to-end trainable pipeline, HybridTabNet, for table detection in scanned document images. Our two-stage table detector uses the ResNeXt-101 backbone for feature extraction and Hybrid Task Cascade (HTC) to localize the tables in scanned document images. Moreover, we replace conventional convolutions with deformable convolutions in the backbone network. This enables our network to detect tables of arbitrary layouts precisely. We evaluate our approach comprehensively on ICDAR-13, ICDAR-17 POD, ICDAR-19, TableBank, Marmot, and UNLV. Apart from the ICDAR-17 POD dataset, our proposed HybridTabNet outperformed earlier state-of-the-art results without depending on pre- and post-processing steps. Furthermore, to investigate how the proposed method generalizes unseen data, we conduct an exhaustive leave-one-out-evaluation. In comparison to prior state-of-the-art results, our method reduced the relative error by 27.57% on ICDAR-2019-TrackA-Modern, 42.64% on TableBank (Latex), 41.33% on TableBank (Word), 55.73% on TableBank (Latex + Word), 10% on Marmot, and 9.67% on the UNLV dataset. The achieved results reflect the superior performance of the proposed method.

Keywords: table detection; table localization; deep learning; hybrid task cascade; object detection; deformable convolution; deep neural networks; computer vision; scanned document images; document image analysis



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1. Introduction

Rapid growth in the digitization of documents has alleviated the demand for methods that can process information accurately and efficiently. Due to the size of the corpus, it has become impractical to employ humans to extract the information. Along with the text, the digital documents contain various graphical page objects, such as tables, figures, and formulas [1]. While state-of-the-art OCR (Optical Character Recognition) [2–4] systems can process the raw text in document images, they are vulnerable to extracting information from graphical page objects [5].

Hence, it is important to first localize these page objects in document images such that the information can be retrieved accurately. Tables are one of the most important page objects in documents because they summarize a major piece of information compactly and precisely. In this paper, we have taken a step forward towards improving the table detection methods in document images.

It has already been established in the community of table understanding [6–12] that table detection in document images hold two major challenges: (1) low inter-class variance (between different classes, such as tables, figures and charts) and (2) high intra-class variance (within the single class, such as tables with and without ruling lines). Due to these challenges, it is highly complex to come up with custom heuristics that can assist in developing robust and generic table detection system [13].

Thus far, we have seen a similar trend in the advancement of object detection algorithms in computer vision [14–17] with the progress in table detection systems [6–8,11,12]. Although recent object detection frameworks have noticeably improved the performance of table detection approaches [7,18], there is room in further reducing the close false positives. These case of close false positives can be resolved by leveraging the instance segmentation networks where an additional segmentation loss is added along with the bounding box and classification loss [12,17,19].

In this paper, we advanced the research for the problem of table detection in scanned document images by introducing the idea of implementing novel state-of-the-art hybrid task cascade networks [20] equipped with deformable convolutions [21]. Unlike prior methods, the proposed technique neither relies on preprocessing methods to transform the raw document images nor requires any rule-based post-processing method to refine the predictions. Moreover, the introduced method is not only applicable for scanned document images but also for PDF documents. Furthermore, the added deformable convolutions in our employed ResNeXt-101 backbone network solve the problem of detecting tables with arbitrary layouts.

In particular, the contributions of this paper are summarized as follows:

- We propose HybridTabNet, a novel table detection system by incorporating deformable convolutions in the backbone network of an instance segmentation-based Hybrid Task Cascade (HTC) network.
- During our exhaustive evaluation, we accomplish state-of-the-art performance on five well-recognized publicly available datasets for table detection in scanned document images.
- We present the superiority of the proposed method by reporting results with a leave-one-out scheme on several table detection datasets. The employed strategy sets a new direction, indicating the generalization capabilities of the proposed method.

The remaining paper is organized as follows: Section 2 briefly discusses the earlier literature available on the task of table detection. Section 2.1 talks about the rule-based methods, whereas Section 2.2 highlights learning-based approaches. Section 3 explains the proposed table detection framework by discussing the employed deformable convolutions, backbone network, and object detection algorithm. Section 4 describes the essential details of the datasets that are utilized in the experiments. Section 5 explains the evaluation criteria, whereas Section 6 provides the experiment details and presents both a quantitative and qualitative analysis of the proposed method. Section 7 concludes the paper and outlines possible future directions.

2. Related Work

Table understanding is an integral step towards document image analysis. Over the past few decades, several researchers have presented solutions for the task of detecting tables having arbitrary layouts in documents. Earlier, most of the proposed methods either relied on custom heuristics or leveraged the external meta-data information to tackle the problem of table detection [22–26]. Later, researchers exploited statistical learning [27] followed by deep-learning-based approaches to alleviate the generalization capabilities of table detection systems [6–8,10–12,28–32]. This section presents a brief overview of some of these approaches.

2.1. Rule-Based Approaches

Based on our knowledge, the first work on detecting tables in document images was introduced by Itonori et al. [22] in 1993. The approach defines the table as a block of text that follows fixed constraints. In that same year, Chandran and Kasturi [24] developed a table detection method that relies on vertical and horizontal lines. Pyreddy and Croft [33] presented a system that leverages the custom heuristics to retrieve structural elements from text and separates tabular areas from the extracted elements.

Pivk et al. [34] published a system that is capable of transforming tables embedded in HTML documents into logical structures. This work defines the set of relevant table layout, which are exploited to extract tables. Along with tabular layouts, grammar was defined to recognize tables in documents [26]. Hu et al. [35] proposed a table detection method relying on the correlation of white spaces and vertical connected component analysis. For the comprehensive summarization of these rule-based approaches, readers may refer to [13,36–39].

Although these rule-based methods work well on documents with similar tabular layouts, they are laborious in terms of finding optimal heuristics. Furthermore, these conventional approaches are vulnerable to producing generic solutions. Therefore, approaches with better generalization capabilities are required to solve the problem of table detection in document images.

2.2. Learning-Based Approaches

Kieninger and Dengel [40] introduced T-Recs, which is a clustering approach to detect tables in documents. Later, in a follow up work, PDF-TREX [41] is proposed. This method applied T-Recs to extract tables from PDF documents. Along with unsupervised learning [40,42], supervised learning was exploited to detect tables in documents [43].

The proposed system, Tabfinder, transforms a document into an MXY tree representation. Subsequently, the method proposes the possible tables by looking for the blocks that are enclosed in vertical and horizontal ruling lines. Hidden Markov Models (HMMs) [44,45] and the combination of SVM classifier and custom heuristics [46] has also been exploited to produce table detection methods that depend on visible ruling lines in tables. Although machine learning-based methods have improved the performance of table detection systems, they either rely on the additional meta-data information or tables having specific layouts, such as the presence of ruling lines and so on.

With the recent surge of deep learning-based algorithms in computer vision, a similar trend can be seen in the table understanding community. To begin with, Hao et al. [47] implemented a deep Convolutional Neural Network (CNN) to extract spatial features, which were later combined with custom heuristics and meta-information from PDF to classify the tabular regions in documents. Later object detection algorithms [10,14–17] were heavily explored to develop robust and data-driven image-based table detection systems [6,8–12,28,30].

Gilani et al. [11] employed Faster R-CNN [15] to detect tables in document images. In this work, the raw document images were first transformed by modifying their pixel values using the distance transform mechanism. These transformed images were fed to the object detection network to aid the process of recognizing tabular structures. An end-to-end image based table detection method was published by Schreiber et al. [6]. The proposed method exploited Faster R-CNN [15] with a pretrained backbone (ZFNet [48] and VGG-16 [49]).

The system GOD (Graphical Object Detection) [12] is an object detection framework that detects graphical page objects in document images. In the proposed work, the author empirically claimed that Mask R-CNN [16] worked better as compared to Faster R-CNN [15] in recognizing graphical page objects in scanned document images. A similar conclusion was presented by Zhong et al. [50] in which their novel proposed dataset PubLayNet was evaluated on both Faster and Mask R-CNN.

Instead of conventional convolutions, Siddiqui et al. [7] employed deformable convolutions to detect tables in document images. The authors empirically established that the dynamic receptive field of deformable convolutions adapted better in detecting tabular boundaries with arbitrary layouts. In another work, Faster R-CNN [29] was employed to tackle the problem of table detection in document images. The final tabular area was retrieved by refining the corners of predicted tabular boundaries. Vo et al. [30] presented an ensembling technique in which Fast R-CNN [14] and Faster R-CNN [15] were combined to detect graphical page objects in document images.

Since tabular images are limited in number, several of the above-mentioned approaches leverage fine-tuning techniques [6,7,11]. In one of the recent works [28], it has been proposed that close-domain fine-tuning performs better as compared to open-domain fine-tuning for detecting tables in document images. In order to establish this conclusion, the authors exploited Mask R-CNN [16], RetinaNet [51], SSD [52], and YOLO [53] to perform the task of table detection.

CascadeTabNet [8] is an end-to-end table detection system that operates on Cascade Mask R-CNN, which is an extension of Cascade R-CNN [17]. Along with the novel object detection network, the proposed approach relies upon transfer learning, image transformation, and data augmentation techniques to produce state-of-the-art results for table detection in document images.

3. Method

Figure 1 illustrates the pipeline of the proposed HybridTabNet. It comprises a ResNeXt-101 [54] with deformable convolution layers and a Hybrid Task Cascade network (HTC). ResNeXt-101 extracts feature maps from the dataset, and HTC uses the extracted feature maps to propose regions through Region Proposal Network (RPN). It performs Region of Interest (ROI) align or pooling on the proposed regions, and the bounding box and semantic heads use pooled feature maps to compute bounding boxes and semantic regions. The whole pipeline is trained in an end to end manner. The following sections will describe the essential components of our proposed approach.

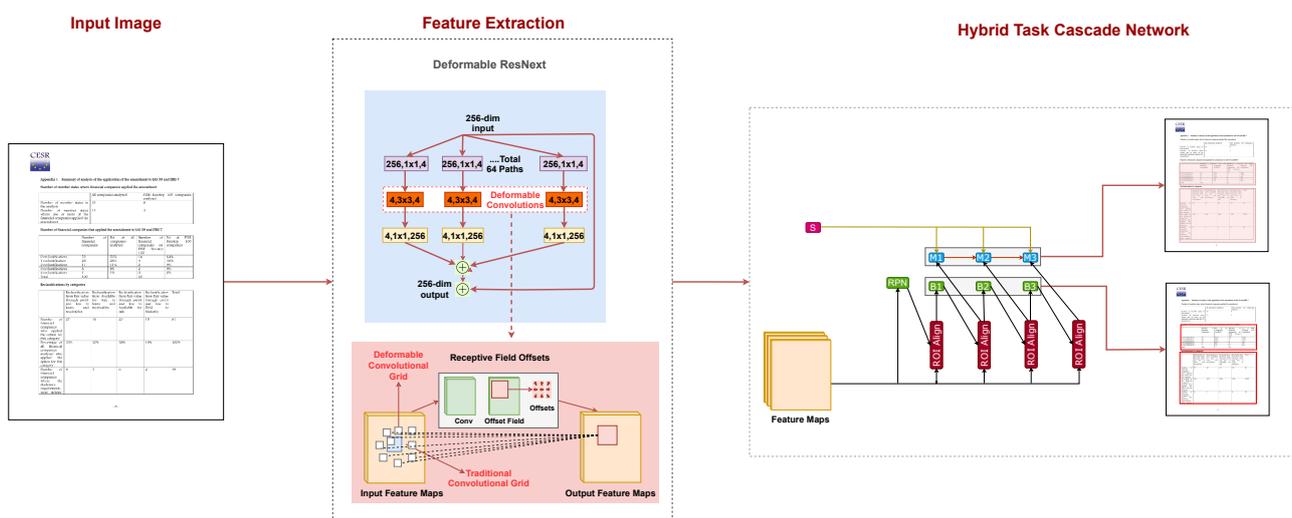


Figure 1. HybridTabNet for Table detection and segmentation. In the first step, the network performs feature extraction using ResNeXt-101 [54] with deformable convolution layers. The second step utilizes the Hybrid Task Cascade network to regress the bounding box and semantic mask coordinates of the table in the image.

3.1. Deformable Convolution

Convolutional Networks [55] have been very successful over the past years on applications, including object detection and segmentation [56–58]. However, they cannot

model complex geometric transformations due to their fixed kernel size. Deformable convolutional layers [21] were introduced to overcome this limitation. The intuition behind deformable convolutional layers is to add 2D offsets at regular grid sampling positions in the standard convolution operation, which deforms the constant receptive field of the preceding activation unit.

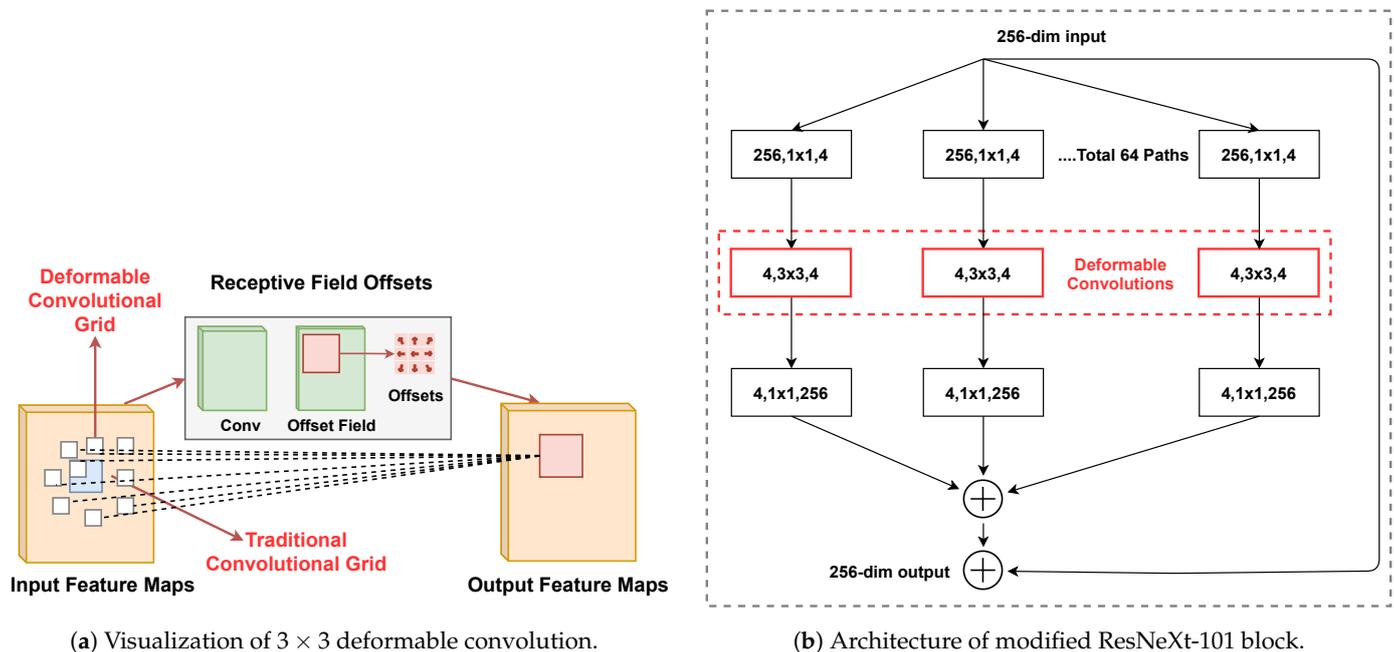
The added offsets are learnable from the preceding feature maps. The receptive fields of the deformable layers are adaptive, which changes according to the scale of the object, and this allows the capture of objects at different scales [21]. The deformable layers use the same number of learnable parameters as convolutional layers, but exploit a much larger receptive field. This makes the performance of deformable layer s superior to that of convolutional layers [21].

The deformable convolution operation can be defined as follows.

$$y(\mathbf{p}_0) = \sum_{\mathbf{p}_n \in \mathcal{R}} \mathbf{w}(\mathbf{p}_n) \cdot x(\mathbf{p}_0 + \mathbf{p}_n + \Delta \mathbf{p}_n) \tag{1}$$

where \mathcal{R} is any kernel of size $n \times n$, \mathbf{w} is the weight of the kernel, x is the input feature map, y is the output of convolution operation, \mathbf{p}_0 is the starting position of each kernel, \mathbf{p}_n is enumerating along with all the positions in \mathcal{R} , and $\Delta \mathbf{p}_n$ denotes the offsets added to the normal convolution operation.

Figure 2a depicts that 2D offsets for the deformable layer are obtained by applying a convolutional layer over the input feature maps. The spatial resolution and dilation of the convolution kernel are the same as in the current convolutional layer. The output channels are of dimension $2N$, where N corresponds to the number of 2D offsets.



(a) Visualization of 3×3 deformable convolution.

(b) Architecture of modified ResNeXt-101 block.

Figure 2. The components of our feature extraction pipeline. Part (a) shows the structure of deformable convolutions where the traditional convolutional grid (in blue) is transformed into deformable grid (in white) by adding 2D offsets. Part (b) shows that the conventional convolutions are replaced with deformable convolutions in ResNeXt-101 to extract tables at multiple scales.

3.2. ResNeXt-101

ResNeXt [54] is a variant of ResNet [59], and it exposes a new dimension called Cardinality along with the width and depth. Cardinality defines the size of the transform set, which greatly contributes to the performance of ResNeXt [54]. Experiments demonstrated that cardinality showed better performance than going wide and deep [54]. We used

ResNeXt-101 as a backbone for feature extraction with Cardinality = 64 and bottleneck width = 4d. Figure 2b illustrates that the convolutional layers in blocks c3–c5 are replaced by deformable layers.

3.3. Hybrid Task Cascade

Cascade architecture has been very successful and effective in tasks, such as object detection [17]. However, to successfully apply the idea of cascade architecture to instance segmentation problems was still an open-ended research question until HTC [20] was introduced. The main idea behind HTC is to leverage the relationship between object detection and segmentation tasks. Instead of treating detection and segmentation as different problems, it performs joint multi-stage processing.

The joint multi-stage processing refers to the combination of object detection and segmentation at each stage. Due to the joint multi-stage processing, the improvement in one task, e.g., detection, improves the mask prediction and segmentation task [20]. It also utilizes the spatial context to distinguish the background from the foreground. The semantic branch (S) provides spatial cues, which complement the bounding box and mask features.

Figure 3 exhibits the architecture of HTC. It has multiple heads for both bounding box and semantic segmentation to process input at different scales. It consists of a segmentation branch (S) with mask (M1,M2,M3) and bounding box (B1,B2,B3) heads. The RPN head predicts preliminary object proposals for these feature maps, whereas the semantic segmentation branch predicts per-pixel semantic segmentation for the whole image through a fully convolutional architecture trained jointly with other branches.

In the first stage of architecture, the RPN head applies RoI pooling to the output features maps of the backbone model. B1 takes the output of RoI pooling as an input to make RoI-wise predictions. Each head makes two predictions: bounding box classification scores and box regression points. In the second stage, M1 generates pixel-wise segmentation masks for positive RoIs. The rest of the stages follow the same flow. At the inference time, object detection made by Bbox heads is complemented with segmentation masks made by the mask head for all detected objects.

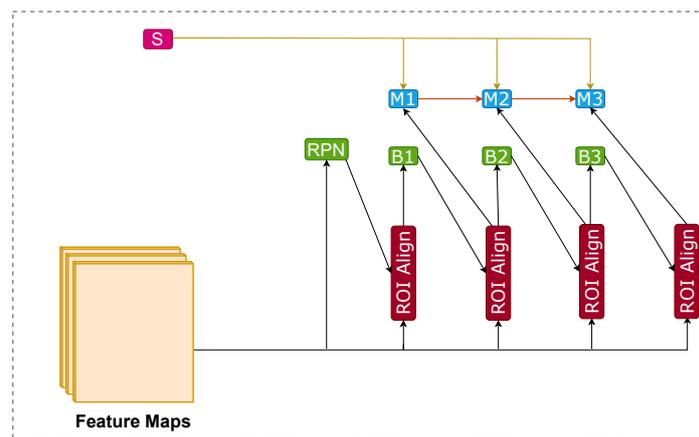


Figure 3. Explained architecture of the Hybrid Task Cascade Network. This network utilizes three box and mask heads in a cascading architecture to produce accurate predictions.

Equation (2) explains the flow of Figure 3.

$$\begin{aligned}
 \mathbf{x}_t^{box} &= \mathcal{P}(\mathbf{x}, \mathbf{r}_{t-1}) + \mathcal{P}(S(\mathbf{x}), \mathbf{r}_{t-1}) \\
 \mathbf{r}_t &= B_t(\mathbf{x}_t^{box}) \\
 \mathbf{x}_t^{mask} &= \mathcal{P}(\mathbf{x}, \mathbf{r}_t) + \mathcal{P}(S(\mathbf{x}), \mathbf{r}_t) \\
 \mathbf{m}_t &= M_t(\mathcal{F}(\mathbf{x}_t^{mask}, \mathbf{m}_{t-1}^-))
 \end{aligned}
 \tag{2}$$

where S indicates the semantic segmentation head, \mathbf{x} indicates the CNN features of backbone network, and \mathbf{x}_t^{box} and \mathbf{x}_t^{mask} indicate the box and mask features derived from \mathbf{x} and the input RoI. $\mathcal{P}(\cdot)$ is a pooling operator, which could be RoI Align or RoI pooling; B_t and M_t denote the box and mask head at the t -th stage; and \mathbf{r}_t and \mathbf{m}_t represent the corresponding box predictions and mask predictions. Equation (2) indicates that the box and mask heads of each stage take RoI features extracted by the backbone network and semantic features given by semantic segmentation head. It is essential for HTC because it can differentiate between tables in a cluttered background by exploiting the semantic features.

Since the modules given in Equation (2) are differentiable [20]. HTC can be trained in an end-to-end manner. The overall loss function can be formulated in the form of multi-tasking [20] learning.

$$\begin{aligned} \mathcal{L} &= \sum_{t=1}^T \alpha_t (\mathcal{L}_{bbox}^t + \mathcal{L}_{mask}^t) + \beta \mathcal{L}_{seg}, \\ \mathcal{L}_{bbox}^t(c_t, \mathbf{r}_t, \hat{c}_t, \hat{\mathbf{r}}_t) &= \mathcal{L}_{cls}(c_t, \hat{c}_t) + \mathcal{L}_{reg}(\mathbf{r}_t, \hat{\mathbf{r}}_t), \\ \mathcal{L}_{mask}^t(\mathbf{m}_t, \hat{\mathbf{m}}_t) &= BCE(\mathbf{m}_t, \hat{\mathbf{m}}_t) \\ \mathcal{L}_{seg} &= CE(\mathbf{s}, \hat{\mathbf{s}}). \end{aligned} \quad (3)$$

where \mathcal{L}_{bbox}^t is the loss of the bounding box predictions at stage t , and it combines two terms \mathcal{L}_{cls} and \mathcal{L}_{reg} , respectively, for classification and bounding box regression. \mathcal{L}_{mask}^t is the loss of mask prediction at stage t , which adopts the binary cross entropy form as in Mask R-CNN [16]. \mathcal{L}_{seg} is the semantic segmentation loss in the form of cross entropy. BCE represents the binary cross entropy loss, and CE denotes the cross entropy loss [60,61]. The coefficients α_t and β are used to balance the contributions of different stages and tasks. For all the experiments, we chose $\alpha_t = [1, 0.5, 0.25]$ and $\beta = 1$ [20].

4. Datasets

4.1. ICDAR-13

ICDAR-2013 [62] is a widely used dataset not only for the problem of table detection but also for table structure recognition. The dataset consists of PDF files that are converted into images to perform an image-based table detection method. There are a total of 238 images that are utilized in evaluating our approach. In order to obtain a direct comparison with prior state-of-the-art-approaches [6,7], we used an IoU threshold of 0.5 to calculate the f1-score.

4.2. ICDAR-17 POD

ICDAR-2017-POD (Page Object Detection) [1] is another dataset that was released at ICDAR in 2017. Along with tables, the dataset also has information for the boundaries of figures and formulas. This is a larger dataset than ICDAR-13 [62]. The dataset consists of 2417 images in total, where 1600 images are used for the training purpose, and 817 images are employed in testing. Since the prior works [7] were evaluated with IoU thresholds of 0.6 and 0.8, we also evaluated our approach in the same manner.

4.3. ICDAR-19

ICDAR-2019 [63] is the outcome of the recently organized competition for table recognition at ICDAR 2019. This novel dataset contains two types of document images (modern and historical). Modern document images were retrieved from scientific papers and commercial documents whereas the archival part of the dataset contains hand-written document images. As suggested in the competition, for the modern part of the dataset, 600 images were allocated for training, whereas 240 images were for testing. Similarly, for the historical part, 600 images were assigned for training, and 199 images are adopted for the testing.

4.4. Marmot

Before the advent of TableBank [64], Marmot was one of the largest publicly available datasets for the task of table detection. The Institute of Computer Science and Technology

(Peking University) proposed this dataset, which was later elaborated by Fang et al. [65]. The dataset consists of 2000 images, where a ratio of almost 1:1 is present between the positive to negative samples. Since the original version of the dataset has few incorrect annotations, we employed the corrected version of the dataset from [6]. Hence, instead of 2000, 1967 images were utilized in our evaluation.

4.5. UNLV

UNLV dataset is one of the most recognized datasets in the document analysis community. In general, the dataset is comprised of almost 10,000 document images. However, only 427 of them contain tables. In our experiments, we only utilized the document images that contained tabular information.

4.6. TableBank

Li et al. [64] introduced TableBank as one of the most prominent datasets in the table community. Since this dataset has 417,000 document images, we use this dataset to train our network. It is essential to highlight that, instead of the whole dataset, we utilized 1500 images each from Word and Latex split and 3000 images from the Word + Latex split to compare our results with prior state-of-the-art approaches [8].

5. Evaluation Metrics

In this section, we discuss the evaluation criteria used to evaluate our approach to table detection. We used similar evaluation metrics to current state-of-the-art approaches [7,8,12] for comparison with our results.

The precision, recall, and F1-scores were calculated on IoU [66,67] thresholds of 0.5, 0.6, 0.7, 0.8, and 0.9.

5.1. Intersection of Union

The Intersection over Union (IoU) [66,67] is one of the most prominent evaluation metrics used in object detection benchmarks. It measures the overlap between predicted and ground truth data. A higher value of IoU means that there is more overlap in the predicted and ground truth regions. We used IoU thresholds from 0.5, 0.6, 0.7, 0.8, and 0.9 to evaluate our table predictions. The formula for IoU is summarized in Equation (4).

$$IoU = \frac{\text{Area of Intersection}}{\text{Area of Union}} \quad (4)$$

5.2. Precision

Precision is the ratio of correctly predicted observations to the total predicted observations. Equation (5) depicts the formula of precision.

$$Precision = \frac{\text{True Positives}}{\text{True Positives} + \text{False Positives}} \quad (5)$$

5.3. Recall

Recall is the ratio of correctly predicted observations to the total observations in ground truth. Equation (6) depicts the formula of recall.

$$Recall = \frac{\text{True Positives}}{\text{True Positives} + \text{False Negatives}} \quad (6)$$

5.4. F1-Score

F1-score is the harmonic mean of precision and recall. Equation (7) exhibits the formula of the F1-score.

$$F1\text{-score} = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}} \quad (7)$$

5.5. Weighted-Average

We evaluated the F1-score at IoU thresholds 0.5, 0.6, 0.7, 0.8, and 0.9 and report the weighted-average (W.Avg) on the datasets. This allows us to give more importance to f1-scores, precision and recall with higher IoU thresholds. Equation (8) depicts the formula of the weighted-average.

$$\text{Weighted-Average} = \frac{\sum_{n=0.5}^{0.9} n \times S_n}{\sum_{n=0.5}^{0.9} S_n} \quad (8)$$

where n represents the IoU threshold and S_n highlights the score achieved on a specific IoU threshold, ranging from 0.5 to 0.9. The weighted- average precision, recall, and F1-score were all calculated in a similar fashion.

6. Experiments and Results

To perform all of our experiments, we used the MMDetection [68] framework, an open-source framework for object detection based on Pytorch [69]. We used HTC with backbone models ResNet-50 [59] and ResNeXt-101 [54] with deformable convolutions on different datasets to extract the best possible results. We use the configuration files *resnet50_fpn* and *rexnext101_64x4d_fpn_c3-c5_deconv* (cardinality = 64 and Bottleneck width = 4 with deformable convolutions in resnet stage 3 to 5) from MMDetection [68] to implement our backbone models. Both of the models were pretrained on the COCO-2017 [70] dataset and used a Feature Pyramid Network (FPN) [71] neck. FPN extracts features at multiple spatial scales to obtain both low and high-level structures in an image.

ResNet-50 [59] uses a learning schedule of $1\times$, whereas ResNeXt-101 [54] uses a 20e learning schedule. Both of the learning schedules use Adam's optimizer with an initial learning rate of 1.25×10^{-4} with a step-based learning rate decay policy. The learning schedule of $1\times$ decays initial learning rate decays by a factor of 10 at the 8 and 16th epochs. Similarly, the learning rate schedule of 20e decays the initial learning rate by a factor of 10 at the 16th and 19th epochs. We used a batch size of 1 in all of our experiments.

We evaluated our results on the IoU thresholds of 0.5, 0.6, 0.7, 0.8, and 0.9, which allowed us to perform direct comparison with state-of-the-art approaches [6–8,12] in table detection and segmentation.

In the subsequent sections, we discuss our results on different datasets and compare them with state-of-the-art methods.

6.1. ICDAR-19

We finetuned HybridTabNet [20] with backbone models i.e., ResNet-50 [59] and ResNeXt-101 [54] on ICDAR 2019 Track-A Modern dataset [63]. For training and evaluation of our approach, We used the official train-test split given by ICDAR 2019 [63]. Table 1 summarizes the quantitative results of our approach. Our approach achieved the highest precision of 0.953 and a recall of 0.952 on a lower IoU threshold of 0.5 with the ResNeXt-101 backbone. However, from the IoU threshold of 0.5 to 0.8, there was only a slight decline in f1-scores.

This shows that the performance of our approach was not only limited to the lower IoU threshold. ResNet-50 backbone achieved the highest precision of 0.928 and a recall of 0.920 at the 0.5 IoU threshold, which is lower than the ResNext-101 backbone. Moreover, compared to ResNeXt-101 W.Avg of 0.928, the W.Avg of f1-score for ResNet-50 was only 0.887. Therefore, in the succeeding datasets, HybridTabNet used only ResNeXt-101 with deformable convolutions as the backbone in our experiments.

Figure 4 presents the qualitative results of the HybridTabNet on the ICDAR-2019 dataset. In Figure 4b, this network confused a group of bar charts with the table, whereas in Figure 4c, it failed to detect a table without a boundary.

Table 1. HybridTabNet results on the ICDAR-19 dataset with deformable ResNeXt-101 and ResNet-50 backbones. W.Avg denotes the weighted-average of the respective measure on the IoU threshold.

Backbone	IOU Threshold	Precision	Recall	F1-Score
ResNeXt-101	0.5	0.954	0.953	0.953
	0.6	0.937	0.948	0.942
	0.7	0.927	0.948	0.933
	0.8	0.920	0.9331	0.927
	0.9	0.895	0.905	0.901
	W.Avg	0.923	0.934	0.928
ResNet-50	0.5	0.928	0.920	0.924
	0.6	0.905	0.922	0.913
	0.7	0.894	0.910	0.902
	0.8	0.879	0.895	0.887
	0.9	0.831	0.846	0.838
	W.Avg	0.881	0.894	0.887

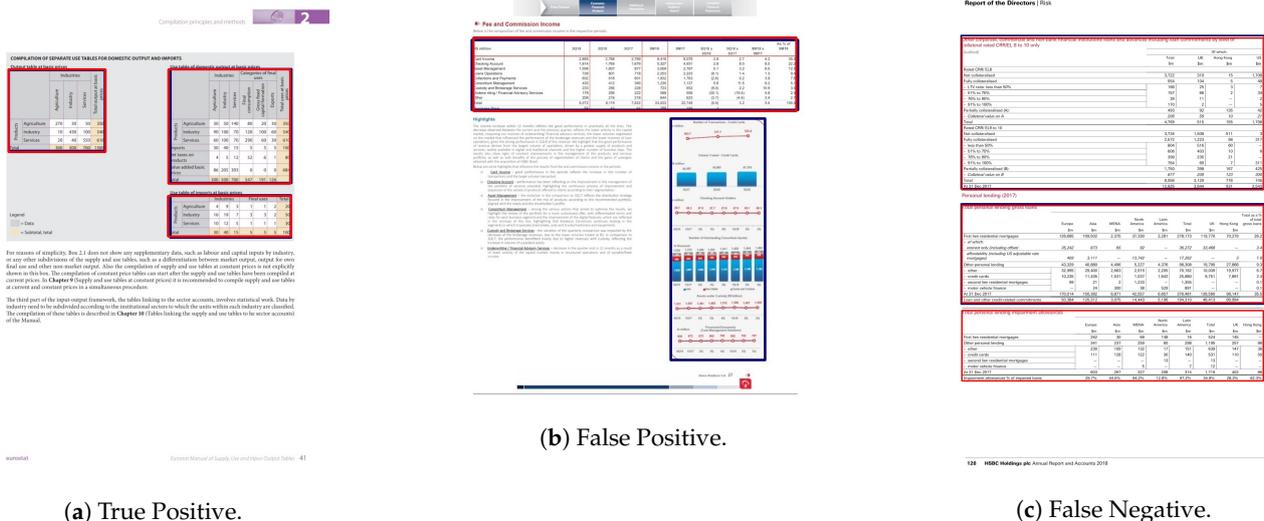


Figure 4. HybridTabNet results on ICDAR-2019 Track-A Modern dataset. (a–c) True positive, False positive, and False negative results, respectively. The blue outline shows the predicted table, and the red outline highlights the ground truth table.

6.2. ICDAR-17 POD

We finetuned HybridTabNet with a ResNeXt-101 backbone on the ICDAR-17-POD [1] dataset. Table 2 quantifies the results of HybridTabNet on the ICDAR-17-POD dataset. This achieved the highest precision of 0.882 and recall of 0.997 on the IoU thresholds of 0.5 to 0.8. On the IoU threshold 0.9, it achieved a recall of 0.983 and precision of 0.869. Overall, the recall value was high and close to 1, whereas the precision value was low. This result means that it rarely failed to detect the table region in the image but also incorrectly labeled regions as tables. Figure 5 depicts the qualitative results of HybridTabNet. Figure 5b shows a False Positive predicted by our model where it confused an image containing a graph as a table. Figure 5c shows a False Negative of our approach where it failed to detect a clear table.

Table 2. HybridTabNet results ICDAR-17 POD results with a deformable ResNeXt-101 backbone. W.Avg denotes weighted-average of the respective measure on the IoU threshold.

Model	IOU Threshold	Precision	Recall	F1-Score
HybridTabNet	0.5	0.882	0.997	0.936
	0.6	0.882	0.997	0.936
	0.7	0.882	0.997	0.936
	0.8	0.879	0.994	0.933
	0.9	0.870	0.983	0.926
W.Avg		0.878	0.993	0.932

Table 10. Marginal effects from binomial logit model —Probability of being active (males, 15–64)

	Urban	Rural	Country
Individual			
Marital status (reference: married)	0.000	0.001	0.000
Marital status (reference: married)	-0.013	-0.007	-0.007
Region (reference: Lower Egypt)	-0.200	-0.200	-0.200
Upper Egypt	-0.022 **	-0.001	-0.007
Age group (reference in 35–44)			
Age 15–24	-0.112 ***	-0.118 ***	-0.111 **
Age 25–34	-0.004	0.000	0.000
Age 45–54	-0.021	-0.019	-0.025
Age 55–64	-0.088	-0.088	-0.088
Age 55+	-0.193 ***	-0.113 ***	-0.292 ***
Head of household	-0.131	-0.131	-0.131
Head of household	-0.062 ***	-0.068 ***	-0.119 ***
Head of household	-0.260	-0.301	-0.092
Head of household	0.002	0.000	0.004
Educational attainment (in schooling in reference)			
Less than basic	0.010	0.015 ***	0.000 ***
Basic education	0.000	0.000	0.000
Secondary and technical	-0.010	-0.140 ***	-0.164 ***
High education	-0.010	0.000	-0.007
University	0.000	0.000	0.000
Higher education	0.000	-0.016	-0.001
Household assets	0.011	0.011	0.011
Presence of livestock	0.701	0.701	0.701
Size of household (in acres)	0.001	0.001	0.000
Community-level variables			
Log mean agricultural wage	0.000	0.000	0.000
Proportion of landless households	0.000	0.000	0.000
Average agricultural plot size (in acres)	0.000	0.000	0.000
Social Capital Index	0.000	0.000	0.000
Economic Capital Index	0.000	0.000	0.000
Log likelihood function	-743.5	-962.4	-719.8
Log likelihood function	-743.5	-962.4	-719.8

We cluster design of the survey. The marginal effects are calculated for changes from the 1st dummy variable and for variables measured at proportions and inflation changes for continuous variables. The reference individual is 25 to 44 years of age, married, and a household head. Lives in Lower Egypt and has one acre in extent. In rural area, he lives in a household with one livestock and has the average amount of land. *** Significant at the 1 percent level, ** significant at the 5 percent level, * significant at the 10 percent level.

(a) True Positive.

(b) False Positive.

Figure 5. HybridTabNet results on the ICDAR-2017 dataset. (a–c) True positive, False positive, and False negative results, respectively. The blue outline shows the predicted table, and the red outline highlights the ground truth table.

6.3. TableBank

TableBank [64] is a unique dataset that comprises three types of documents, i.e., Latex, Word, and a mixture of Latex and Word documents. It has a separate dataset for each document type. We used a smaller train-test split for training, which was defined by the current state-of-the-art approach [8]. This allowed us to perform a direct comparison of our results with their results. We performed finetuning of HybridTabNet on each of the three datasets in the TableBank dataset.

Table 3 summarizes the results of HybridTabNet on TableBank dataset. It achieved the highest F1-score of 0.980 on the 0.5 IoU threshold in Latex documents. There was only a slight drop in the f1-score of HybridTabNet from IoU thresholds of 0.6 to 0.8, which shows that its performance was not limited to lower IoU thresholds. However, at the IoU threshold of 0.9, there was a significant drop in the performance of our approach. Similarly, in Word and a mixture of Latex and Word documents, the F1-score almost remained constant from 0.5 to 0.8. For the IoU threshold of 0.9, the F1-score of Word was similar to lower thresholds, i.e., from 0.5 to 0.8. Conversely, for the mixture of Latex and Word, the F1-score at 0.9 was low.

PatManQL: A language to manipulate patterns & data in hier. catalogs 2-11

Searching for paths that lead to lenses including nodes photo and lenses requires a selection operation: $\varphi_2 = \sigma_{<>< />photo/lenses} \circ \tau_{< > \tau_{< >}$. A final projection will produce a TSR only for lenses (see Figure 10(c)): $\pi_{< model, price > < > \varphi_2}$.

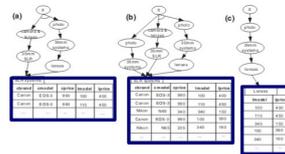


Fig. 10. Manipulating TSRs (II)

5 Discussion and Conclusions

In this work we presented a framework to manipulate path-like patterns and data in hierarchical catalogs. We modified hierarchical catalogs using catalog schemas and we introduced tree-structured relations (TSRs) to represent the different ways of accessing a resource item in a set of catalog schemas. TSRs maintain alternative path-like pattern versions and complex patterns. Considering paths in these structures as knowledge artifacts to group raw data sharing common properties, we suggested PatManQL, a set of operators for TSRs to manipulate paths together with the raw data: select, project, cartesian product, union, intersection and difference. Also, we showed examples of using such operators to manipulate hierarchical catalogs.

We have developed the prototype system PatMan [2] with a query execution engine that implements the suggested operators and a storage mechanism for TSRs (see Figure 11). TSRs can be stored (a) using plain XML files or (b) using the MySQL RDBMS system that PatMan exploits, with a relational schema that follows the all-edges-in-one-table example [3]. The systems retrieves TSRs using either the XML file manager (XFM) or the Database Manager (DM) and evaluates the query expression in main memory using the Query Execution Engine (QE).

We plan to extend the work presented in this paper along several directions. First, we will further explore the role of paths as knowledge artifacts in hierarchical catalogs, searching for useful comparison operators for paths. Also, we

Table 6: Model Equations

Equations	Domain	Description
1 $w_{1a} = w_{1a}(p_1; Z_a, T_a)$	$h \in H$	agricultural shadow wage
2 $w_{2a} = w_{2a}(p_2; Z_a)$	$h \in H$	informal wage
3 $w_a = \frac{1}{\rho} w_{2a} + w_{1a} \frac{\rho}{\rho}$	$h \in H$	agricultural marginal productivity
4 $X_{1a} = X_{1a}(p_1, w_1; T_a)$	$h \in H$	agricultural value added
5 $L_{1a}^d = L_{1a}^d(p_1, w_1; T_a)$	$h \in H$	agricultural labor demand
6 $L_{2a}^d = L_{2a}^d(p_2, w_2; T_a, Z_a)$	$h \in H$	total labor supply
7 $L_{2a}^s = L_{2a}^s - L_{2a}^d$	$h \in H$	informal labor supply
8 $Y_a = p_1 \cdot X_{1a} + w_{2a} \cdot L_{2a}^s + V_a$	$h \in H$	total income
9 $mp_{2a} = mp_{2a}(V_a)$	$h \in H$	marginal propensity to save
10 $C_{1a} = \alpha_a + \frac{\rho}{\rho} \frac{\rho}{\rho} Y_a \cdot (1 - mp_{2a}) - \sum_{i=1}^{\rho} p_i g_{1a} \frac{\rho}{\rho} \quad h \in H, i \in I$	$h \in H, i \in I$	linear expenditure system

Aggregation equations

11 $X_a^T = \sum_{h \in H} \sum_{i \in I} \frac{\rho}{\rho} X_{1a}^T \frac{\rho}{\rho} + \sum_{i \in I} \frac{\rho}{\rho} X_{2a}^T \frac{\rho}{\rho}$		aggregate agricultural supply
12 $X_a^T = \sum_{h \in H} \sum_{i \in I} \frac{\rho}{\rho} X_{1a}^T \frac{\rho}{\rho} + \sum_{i \in I} \frac{\rho}{\rho} X_{2a}^T \frac{\rho}{\rho}$		aggregate supply informal
13 $X_a^T = \sum_{h \in H} \sum_{i \in I} \frac{\rho}{\rho} X_{1a}^T \frac{\rho}{\rho} + \sum_{i \in I} \frac{\rho}{\rho} X_{2a}^T \frac{\rho}{\rho}$	$i \in I$	total demand of good i

Balance Equations

14 $X_a^T = X_a^T$	$i \in I$	Balance equation for good i
Indices		
$i, j \in I$		activities and goods
$h \in H$		households
Parameters		
ρ_{ij}		input-output coefficients

(c) False Negative.

Table 3. HybridTabNet results on each document type of TableBank dataset. W.Avg denotes the weighted-average of the respective measure on the IoU threshold.

Dataset	IOU Threshold	Precision	Recall	F1-Score
Latex	0.5	0.977	0.983	0.980
	0.6	0.977	0.982	0.979
	0.7	0.975	0.980	0.978
	0.8	0.969	0.974	0.971
	0.9	0.932	0.937	0.934
	W.Avg	0.963	0.968	0.965
Word	0.5	0.955	0.985	0.970
	0.6	0.953	0.982	0.967
	0.7	0.951	0.980	0.965
	0.8	0.950	0.978	0.964
	0.9	0.948	0.977	0.962
	W.Avg	0.950	0.979	0.965
Both	0.5	0.963	0.986	0.974
	0.6	0.961	0.984	0.972
	0.7	0.959	0.982	0.970
	0.8	0.955	0.978	0.969
	0.9	0.938	0.960	0.949
	W.Avg	0.953	0.976	0.965

Figures 6–8 illustrate the results on Latex, Word, and the mixture of Latex and Word, respectively. Figure 6a, Figure 7a and Figure 8a show the correct predictions of HybridTabNet. Figure 6b shows the over-segmentation of tables, whereas Figure 6c displays the table that our approach failed to detect. Figures 7b and 8b show the case where a figure that is similar to a table was predicted as a table. Analysis of Figures 7c and 8c, show that our approach faced difficulty when the table had no border.

Table 1: Derived parameters for the light curve fits for the divide-white (d-w) and model-ramp (m-r) techniques

Wavelength (μm)	Transit Depth (ppm)	Limb Darkening	χ^2_r			
d-w	m-r	d-w	m-r			
1.135 – 1.158	-39 ± 31	6 ± 3.3	0.27 ± 0.01	0.28 ± 0.01	1.12	1.20
1.158 – 1.181	-28 ± 30	12 ± 3.2	0.26 ± 0.01	0.27 ± 0.01	1.01	1.24
1.181 – 1.204	34 ± 30	29 ± 3.0	0.25 ± 0.01	0.26 ± 0.01	1.04	1.14
1.205 – 1.228	-48 ± 28	-32 ± 2.9	0.26 ± 0.01	0.28 ± 0.01	0.90	1.22
1.228 – 1.251	27 ± 28	25 ± 2.9	0.26 ± 0.01	0.28 ± 0.01	0.85	1.29
1.251 – 1.274	5 ± 27	-6 ± 2.9	0.26 ± 0.01	0.26 ± 0.01	0.97	1.29
1.274 – 1.297	13 ± 27	12 ± 2.7	0.23 ± 0.01	0.23 ± 0.01	1.00	1.50
1.297 – 1.320	14 ± 26	0 ± 2.7	0.23 ± 0.01	0.25 ± 0.01	0.96	1.38
1.320 – 1.343	29 ± 26	2 ± 2.8	0.26 ± 0.01	0.27 ± 0.01	1.08	1.52
1.343 – 1.366	-2 ± 27	-15 ± 2.8	0.20 ± 0.01	0.32 ± 0.01	0.99	1.44
1.366 – 1.389	32 ± 27	35 ± 2.6	0.28 ± 0.01	0.29 ± 0.01	0.97	1.42
1.389 – 1.412	31 ± 27	33 ± 2.8	0.28 ± 0.01	0.29 ± 0.01	0.96	1.39
1.412 – 1.435	-5 ± 27	-33 ± 2.8	0.29 ± 0.01	0.31 ± 0.01	1.15	1.43
1.435 – 1.458	29 ± 29	17 ± 2.8	0.29 ± 0.01	0.30 ± 0.01	1.01	1.39
1.458 – 1.481	-8 ± 28	1 ± 2.9	0.32 ± 0.01	0.33 ± 0.01	1.01	1.33
1.481 – 1.504	27 ± 28	28 ± 2.8	0.28 ± 0.01	0.29 ± 0.01	0.94	1.37
1.504 – 1.527	-11 ± 28	-23 ± 2.9	0.27 ± 0.01	0.29 ± 0.01	1.15	1.58
1.527 – 1.550	20 ± 28	1 ± 2.9	0.27 ± 0.01	0.29 ± 0.01	1.17	1.56
1.550 – 1.573	-21 ± 28	0 ± 2.8	0.28 ± 0.01	0.29 ± 0.01	1.28	1.62
1.573 – 1.596	-65 ± 28	-62 ± 3.0	0.26 ± 0.01	0.28 ± 0.01	1.08	1.46
1.596 – 1.619	-17 ± 28	-6 ± 2.9	0.26 ± 0.01	0.27 ± 0.01	1.34	1.69
1.619 – 1.642	-17 ± 30	-26 ± 3.0	0.22 ± 0.01	0.24 ± 0.01	1.16	1.59

β	α	β	α	β	α
1	$t_1 = 0$	$t_1 = 0$	$t_1 = (21 + \sqrt{21})/42$	$t_1 = 0$	$t_1 = (-3 + \sqrt{21})/6$
4	$t_1 = 0$	$t_2 = (-7 - \sqrt{21})/21$	$t_2 = 0$	$t_2 = 0$	$t_2 = (3 - \sqrt{7})/2$
5	$t_1 = 0$	$t_2 = 1 - 5\sqrt{7}/14$	$t_2 = 0$	$t_1 = (-7 + 5\sqrt{7})/14$	$t_2 = 0$
6	$t_1 = 0$	$t_2 = 0.05801393...$	$t_2 = 0$	$t_1 = 0.41856361...$	$t_2 = 0$
8	$t_1 = 0$	$t_2 = 0.1186937...$	$t_2 = 0$	$t_1 = 0.33811717...$	$t_2 = 0$
12	$t_1 = 0$	$t_2 = 0.22975793...$	$t_2 = 0$	$t_1 = 0.32957499...$	$t_2 = 0$
12	$t_1 = 0$	$t_2 = 0.80219058...$	$t_2 = 0$	$t_1 = 0.22949075...$	$t_2 = 0$
12	$t_1 = 0$	$t_2 = 0.22975793...$	$t_2 = 0$	$t_1 = (\sqrt{3} - \sqrt{7})/2$	$t_2 = 0$

Table 5: Lines parallel to coordinate axes contained in the graphs for $\beta_1 \cap \beta_2$.

β	Node	Coordinates	Function value
5	β_1	(0.22317695, -0.06214532)	11.44128654
12	β_1	(0.38891313, -0.18112906)	11.33397428
12	β_2	(0.38829585, -0.18524212)	11.40972266

Table 6: Critical points inside the ridge for $\beta_1 \cap \beta_2$.

(a) True Positive.

(b) False Positive.

(c) False Negative.

Figure 6. HybridTabNet results on TableBank Latex dataset. (a–c) True positive, False positive, and False negative results, respectively. The blue outline shows the predicted table, and the red outline highlights the ground truth table.

Table 2: Values obtained from β_1 and β_2 for their intersection $\beta_1 \cap \beta_2$ with respect to the xy plane, i.e., assuming counter-clockwise with respect to the xy plane, i.e., the end of the table. On the left table configuration, the right one is counter-clockwise.

β	α	β	α
3	$t_1 = (-3 + \sqrt{21})/6$	$t_1 = 1/2 + \sqrt{21}/42$	$t_1 = 1/2 + \sqrt{21}/42$
4	$t_1 = 17 - \sqrt{21}/21$	$t_2 = 5 - \sqrt{21}/6$	$t_2 = (3 - \sqrt{21})/6$
4	$t_1 = 24 - \sqrt{7}/2$	$t_2 = 1/2 - 3\sqrt{7}/14$	$t_2 = 3 - \sqrt{7}/2$
4	$t_1 = 1 - 5\sqrt{7}/14$	$t_2 = 4 - 3\sqrt{7}/2$	$t_2 = -1/2 + 5\sqrt{7}/11$
5	$t_1 = 0.05801393...$	$t_2 = 0.03375000...$	$t_2 = 0.41786394...$
6	$t_1 = (5 - \sqrt{21})/2$	$t_2 = -1/2 - 3\sqrt{21}/14$	$t_2 = -1/2 - 3\sqrt{21}/14$
8	$t_1 = 0.22949075...$	$t_2 = 0.37922950...$	$t_2 = 0.37922950...$
8	$t_1 = 0.1186937...$	$t_2 = 0.07811309...$	$t_2 = 0.07811309...$
12	$t_1 = 0.32957499...$	$t_2 = 0.80219058...$	$t_2 = 0.80219058...$
12	$t_1 = 0.22975793...$	$t_2 = 0.20871215...$	$t_2 = (5 - \sqrt{21})/2$

Table 3: Values obtained from β_1 and β_2 for their intersection $\beta_1 \cap \beta_2$ with respect to the xy plane, i.e., assuming counter-clockwise with respect to the xy plane, i.e., the end of the table. On the left table configuration, the right one is counter-clockwise.

of them, d_{12} being half filled negatively and the other one, d_{21} almost filled. The number of relevant orbits in total (here for β_1 or β_2) is $d_{12} + d_{21}$, and d_{12} are negative, and d_{21} almost filled, and live in the case of β_1 on the left table, where besides these orbits of β_1 on the left table, there are also the orbits of β_2 on the right table.

In the case of β_1 on the right table, the orbits of β_1 on the right table are also the orbits of β_2 on the left table, and d_{12} and d_{21} are positive. In the case of β_2 , we have additionally the orbits of β_1 on the right table, and d_{12} and d_{21} are negative. In the case of β_1 on the left table, and the d_{12} orbit in the case of the left table, and the d_{21} orbit in the case of the right table.

IV. CO-EXISTENCE AND OUTSIDE NANOTUBES: RESULTS

In the previous section, we showed how to derive the intersection points that should correctly appear in the intersection of the two tables. We now show the intersection points in the intersection of the two tables. We now show the intersection points in the intersection of the two tables. We now show the intersection points in the intersection of the two tables.

A. Co-occurrence (4,4) table, below site

According to DFT, in the geometry C_4 is in a configuration very close to sp^2 , and hence with $\alpha \approx 1/2$. In particular, it has only one truly negative orbital, d_{12} , occupied by the π covalent orbital along with the σ orbit, which is only partially occupied, i.e., only partially occupied, d_{21} orbit is occupied by the π covalent orbital, and the σ orbit is only partially occupied, i.e., only partially occupied, d_{12} orbit is occupied by the π covalent orbital, and the σ orbit is only partially occupied, i.e., only partially occupied, d_{21} orbit is occupied by the π covalent orbital, and the σ orbit is only partially occupied, i.e., only partially occupied.

Table 6. Comparison of HybridTabNet on f1-scores with previous state-of-the-art methods. Our proposed method achieved state-of-the-art performance on every dataset except ICDAR-2017-POD. W.Avg denotes the weighted-average of the respective measure on the IoU threshold.

Dataset	Method	IOU					W.Avg
		0.5	0.6	0.7	0.8	0.9	
ICDAR-2019-TrackA-Modern	TableRadar [63]	–	0.969	0.957	0.951	0.897	0.940
	NLPR-PAL [63]	–	0.979	0.966	0.939	0.850	0.927
	Cascade-TabNet [8]	–	0.943	0.934	0.925	0.901	0.901
	Ours	0.953	0.942	0.933	0.927	0.901	0.928
ICDAR-2017-POD	Fast Detectors [1]	–	0.921	–	0.896	–	–
	PAL [1]	–	0.960	–	0.951	–	–
	GOD [12]	–	0.971	–	0.968	–	–
	DeCNT [7]	–	0.968	–	0.952	–	–
	Ours	0.936	0.936	0.936	0.933	0.923	0.932
ICDAR-2013	Cascade-TabNet [8]	1.0	–	–	–	–	–
	Ours	1.0	–	–	–	–	–
TableBank(Latex)	Cascade-TabNet [8]	0.966	–	–	–	–	–
	Ours	0.980	0.980	0.978	0.971	0.934	0.9661
TableBank(Word)	Cascade-TabNet [8]	0.949	–	–	–	–	–
	Ours	0.970	0.967	0.965	0.964	0.962	0.965
TableBank(Both)	Cascade-TabNet [8]	0.943	–	–	–	–	–
	Ours	0.974	0.972	0.970	0.967	0.949	0.965
Marmot	DeCNT [7]	0.895	–	–	–	–	–
	CDeC-Net [9]	0.952	–	–	0.840	0.769	–
	Ours	0.956	0.953	0.948	0.936	0.901	0.935
UNLV	GOD [12]	0.928	–	–	–	–	–
	CDeC-Net [9]	0.938	0.883	–	–	–	–
	Ours	0.944	0.931	0.931	0.919	0.807	0.898

6.6.2. ICDAR-17

From Table 6, we can observe that the current state-of-the-art approaches [7,12,63] for ICDAR-17 dataset are evaluated only on 0.6 and 0.8 IoU thresholds. We achieve the f1-scores of 0.936 and 0.933 on the IoU thresholds 0.6 and 0.8. If we directly compare our approach results on the mentioned IoU thresholds with current state-of-the-art methods, it is apparent that we do not achieve state-of-the-art performance. The inter-class variance in ICDAR-17 is less, which makes it harder to detect the table regions.

The current state-of-the-art approach [12] on this dataset also learns the difference between a table, figures, and equations. This enable their approach to produce less false positives. However, in our approach, we do not learn such differences between the classes, and instead, we learn the mapping directly for the table class. This leads to lower precision scores but higher recall scores even on higher IoU thresholds. Furthermore, we provide results at 0.5, 0.8, and 0.9 IoU thresholds for the sake of completeness and future benchmarking.

6.6.3. ICDAR-13

Table 6 shows the results of HybridTabNet on the ICDAR-2013 [62] dataset. The current state-of-the-art approach [8] already achieved the perfect f1-score of 1.0 at the 0.5 IoU threshold. Our approach achieved an f1-score of 1.0 at the 0.5 IoU threshold, which is state-of-the-art performance.

6.6.4. TableBank

The TableBank [64] dataset consists of three subset datasets, which are Latex, Word and a mixture of Latex and Word documents. Table 6 shows the comparison of HybridTabNet and the current state-of-the-art approach Cascade-TabNet [8]. Cascade-TabNet evaluates Latex, Word, and a mixture of Latex and Word documents only at the IoU threshold of 0.5. It achieved f1-scores of 0.966, 0.949, and 0.943 on Latex, Word, and their mixture.

We also evaluated our approach on 0.5 and achieved f1-scores of 0.980, 0.970, and 0.974 on Latex, Word and their mixture. If we directly compare the results, we achieve state-of-the-art performance on each subset of TableBank. Moreover, CascadeTabNet [8] applies line correction on the test data as an image postprocessing technique to improve their results. However, we did not use any such image preprocessing or postprocessing techniques. This makes our technique and approach far superior to CascadeTabNet [8]. Furthermore, we also report results on 0.6, 0.7, 0.8, and 0.9 IoU thresholds, which can be used for future benchmarking on the dataset.

6.6.5. Marmot

Table 6 illustrates the comparison of HybridTabNet and the current state-of-the-art approaches DeCNT [7] and CDeC-Net [9]. DeCNT achieved the F1-score of 0.895 on the 0.5 IoU threshold, and CDeC-Net [9] achieved F1-scores of 0.952, 0.840, and 0.769 on the 0.5, 0.8, and 0.9 IoU thresholds. Similarly, our approach achieved F1-scores of 0.956, 0.936, and 0.901 on the 0.5, 0.8, and 0.9 IoU thresholds. The direct comparison of our results with CDeC-Net and DeCNT proves that we achieved state-of-the-art results on the Marmot dataset. We also evaluated our approach on the 0.6 and 0.7 IoU thresholds for future benchmarking on the dataset.

6.6.6. UNLV

The current state-of-the-art approaches GOD [12] and CDeC-Net [9] on UNLV [72] were evaluated on the IoU thresholds of 0.5 and 0.6. Table 6 presents the comparison of HybridTabNet and state-of-the-art approaches on the UNLV dataset. GOD achieved an F1-score of 0.928 on the 0.5 IoU threshold, whereas CDeC-Net achieved an F1-score of 0.938 and 0.883 on the IoU thresholds of 0.5 and 0.6. For a direct comparison, we evaluated our approach from the 0.5 to 0.9 IoU thresholds. We obtained F1-scores of 0.944 and 0.931 on the 0.5 and 0.6 IoU thresholds, which is better than the current state-of-the-art methods, thus, achieving state-of-the-art performance on the UNLV dataset .

6.7. Leave-One-Out Evaluation

This section explores the employed evaluation strategy to measure the generalization and cross datasets performance of HybridTabNet. To the best of our knowledge, this is the first comprehensive cross dataset evaluation study that consists of several datasets. The idea is as follows: we combined all available datasets except one into a single dataset. This new dataset became our training dataset, whereas the dataset that was left out became our test dataset.

In the case of ICDAR-2019-TrackA-Modern, other datasets, such as ICDAR-2017-POD, ICDAR-2013, Marmot, UNLV, and TableBank were combined and became a single training dataset, whereas ICDAR-2019-TrackA-Modern became our test dataset. We repeated this process for all of the datasets, and performance evaluation was done on 0.5 to 0.9 IoU thresholds.

Table 7 presents the results of the leave-one-out evaluation of HybridTabNet. The results were not promising for datasets, including ICDAR-2013, ICDAR-2017-POD, and ICDAR-2019-TrackA-Modern. This is because the union of datasets included Marmot and UNLV, which are different from the ICDAR-2013, ICDAR-2017-POD, and ICDAR-2019-TrackA-Modern datasets. Consequently, the combined training datasets do not resemble the test dataset, and the performance dropped. We achieved f1-scores of 0.962, 0.960, 0.956, 0.949, 0.929, and 0.949 on 0.5 to 0.9 IoU thresholds for the Marmot dataset. These results

are better than the ones presented for Marmot in Table 6, and therefore it achieved state-of-the-art performance. Similarly, the results on TableBank and UNLV are also comparable to the state-of-the-art results.

Table 7. The results of our leave one out dataset strategy. HybridTabNet achieved state-of-the-art performance on the Marmot dataset. W.Avg denotes the weighted-average of the respective measure on the IoU threshold.

Train Dataset	Test Dataset	IOU					W.Avg
		0.5	0.6	0.7	0.8	0.9	
UNLV + ICDAR-2013 + TableBank (Both) + Marmot + ICDAR-2017-POD	ICDAR-2019-Modern	0.823	0.808	0.787	0.767	0.706	0.770
ICDAR-2019-TrackA-Modern + UNLV + TableBank (Both) + Marmot + ICDAR-2013	ICDAR-2017-POD	0.895	0.890	0.884	0.846	0.813	0.860
ICDAR-2019-TrackA-Modern + UNLV + TableBank (Both) + Marmot + ICDAR-2017-POD	ICDAR-2013	0.825	0.825	0.788	0.767	0.619	0.751
ICDAR-2019-TrackA-Modern + UNLV + TableBank (Word) + Marmot + ICDAR-2017-POD + ICDAR-2013	TableBank(Latex)	0.951	0.947	0.944	0.933	0.866	0.923
ICDAR-2019-TrackA-Modern + UNLV + TableBank (Latex) + Marmot + ICDAR-2017-POD + ICDAR-2013	TableBank(Word)	0.932	0.926	0.922	0.917	0.906	0.919
ICDAR-2019-TrackA-Modern + UNLV + Marmot + ICDAR-2017-POD + ICDAR-2013	TableBank(Both)	0.949	0.943	0.940	0.932	0.886	0.926
ICDAR-2019-TrackA-Modern + UNLV + TableBank (Both) + UNLV + ICDAR-2017-POD	Marmot	0.962	0.960	0.956	0.949	0.929	0.949
ICDAR-2017-POD + Marmot + TableBank (Both) + ICDAR-2013 + ICDAR-2019-TrackA-Modern	UNLV	0.808	0.787	0.766	0.711	0.503	0.898

7. Conclusions and Future Work

This paper presents a novel approach, HybridTabNet, for table detection from scanned document images. The approach uses the ResNeXt-101 backbone for feature extraction and also replaces regular convolutions with deformable convolutions. The proposed approach is the Hybrid Task Cascade network for table detection that uses cascade architecture, for instance, segmentation. Our method surpassed the existing state-of-the-art table detection methods in all the datasets except for ICDAR-2017-POD. The relative improvement of error in terms of the weighted average amounted to 27.57% for ICDAR-2019-TrackA-Modern, 42.64% for TableBank (Latex), 41.33% for TableBank (Word), 55.73% for TableBank (Latex + Word), 10% for Marmot, and 9.67% for UNLV. For ICDAR-2013, the proposed approach achieved a perfect score for precision and recall, which is on par with the previous state-of-the-art method.

However, for ICDAR-2017-POD, the proposed approach did not outperform the state-of-the-art methods. This is because ICDAR-2017-POD contains a lot of other graphical page components that are similar to tables. Other methods rely on pre-and/or post-processing to transform the data for favorable results. However, our approach works on raw images. Moreover, we incorporated the leave-one-out evaluation for all the datasets, which demonstrated the algorithm's generalization capabilities—a direction for evaluating table detection algorithms to follow in the future.

An important future direction is the development of generalized table detection methods that can work with various types of tables instead of being tuned for a specific dataset. We plan to extend this work to create a unified representation that eliminates the pre-and post-processing steps. Moreover, another interesting direction can be to explore table structure recognition with the proposed approach. The proposed approach can be used for cell detection directly. Afterward, cells are classified in rows and columns for the interpretation of the complete structure of table. In addition, we can further improve the results using a recently proposed enhanced version of deformable convolution [73].

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