

REAYER: Real-time Earthquake Prediction with Attention-based Sliding-Window Spectrograms

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Abstract

Predicting earthquakes with precision remains an ongoing challenge in earthquake early warning systems (EWS), that struggle with accuracy and fail to provide timely warnings for impending earthquakes. Recent efforts employing deep learning techniques have shown promise in overcoming these limitations. However, current methods lack the ability to capture subtle frequency changes indicative of seismic activity in real-time, limiting their effectiveness in EWS. To address this gap, we propose REAYER, a novel approach for real-time prediction of P- and S-waves of earthquakes using attention-based sliding-window spectrograms. REAYER leverages Mel-Spectrogram signal representations to capture temporal frequency changes in seismic signals effectively. By employing an encoder-decoder architecture with attention mechanisms, REAYER accurately predicts the onset of P- and S-waves moments when an earthquake occurs. We benchmark the effectiveness of REAYER, showing its performance in terms of both accuracy and real-time prediction capabilities compared to existing methods. Additionally, we provide a web-based implementation of REAYER, allowing users to monitor seismic activity in real-time and analyze historical earthquake waveforms.

1 Introduction

Despite the pressing need to alert populations and safeguard essential infrastructure, up til now it is not possible to predict specific earthquakes with certainty, e.g., the Turkey–Syria earthquakes in 2023 [Kwiatak *et al.*, 2023]. Existing earthquake early warning systems (EWS) like the ShakeAlert system used in US West Coast [Kohler *et al.*, 2020] use on-site $\tau_c - P_d$ algorithm to estimate the arrival of a P-phase, which is the primary seismic wave produced by an earthquake. This algorithm is based on τ_c parameter that captures the wave’s dominant period and P_d for its initial amplitude, in combination with classic short-term average and long-term average (STA/LTA) detection approaches [Gao *et al.*, 2021]. Those approaches are limited in their accuracy as

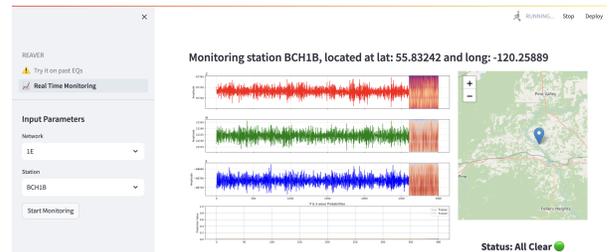


Figure 1: REAYER’s interface, showing real-time monitoring of seismic activity at station BCH1B in Canada. It illustrates Mel-Spectrogram visualizations for three channels (Z, N, E) and the probabilities of P and S waves, with a map indicating the station’s location.

well as the time period between warning and occurrence of the earthquake; furthermore, they cannot generalize to earthquake signals from other regions [Lara *et al.*, 2023].

Recently, deep learning methods were applied to overcome those limitations in EWS. Several methods use fully-connected network, CNNs and RNNs applied on the raw earthquake waveforms to classify between earthquakes and impulsive noises [Ku *et al.*, 2020; Fauvel *et al.*, 2020; Huang *et al.*, 2020; Meier *et al.*, 2019; Mallouhy *et al.*, 2019] or to estimate the magnitude of earthquakes and its source characterization [Munchmeyer *et al.*, 2021; Ochoa *et al.*, 2018]. Furthermore, CNN-based architectures are applied to phase-picking for predicting arrival times of P waves as well as S waves, i.e., more destructive secondary or shear waves of earthquakes, e.g., PhaseNet [Zhu and Beroza, 2019]. This approach is extended by the EQTransformer by employing a combination of CNNs, RNNs and Transformer attention applied on longer 60-seconds waveforms [Mousavi *et al.*, 2020]. While such methods show high detection accuracy of P and S waves, they are trained with raw long waveforms containing centered P or S waves from the earthquake signal. Other methods combine CNN-RNN architectures with Mel-Spectrograms for binary earthquake classification [Shakeel *et al.*, 2021; Mukherjee *et al.*, 2021]. These methods do not capture the instant tiniest changes in frequency when an earthquake occurs and limits their performance in EWS to enable real-time detection of an earthquake. But, predicting an earthquake even just a second before it happens can have significant positive impacts on reducing damage and en-

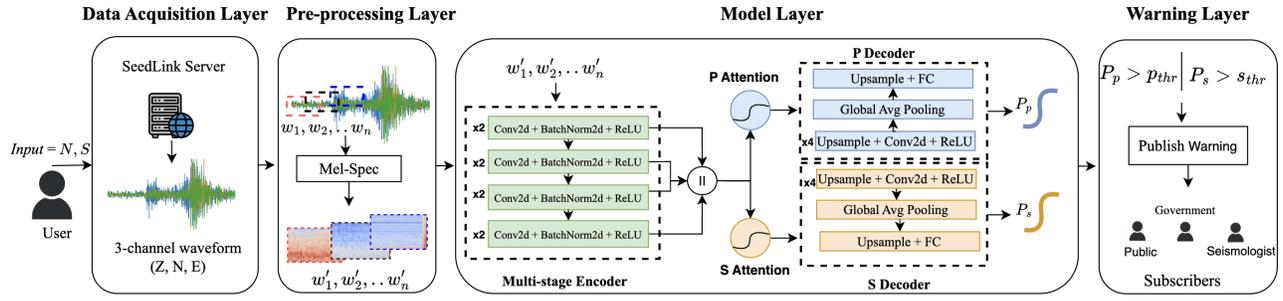


Figure 2: REAVER's Architecture with its four layers: Data Acquisition, Pre-Processing, Model Prediction, and Warning Generation.

71 hancing public safety [McBride *et al.*, 2022], e.g., automated
72 systems activation like shutting off gas lines, brief warnings
73 for allowing people to take cover under a desk or move away
74 from windows and switch of life-support systems in hospitals
75 to emergency power to ensure continuity.
76 In this paper, we propose REAVER - an approach for pre-
77 dicting P- and S-waves of earthquakes in real-time based on
78 attention-based sliding-window spectrograms. Instead of rely-
79 ing on raw 3-channel waveforms, we adopt the widely used
80 Mel-Spectrogram signal representation in sound to represent
81 the frequency amplitudes in each channel in the signal across
82 time [Gong *et al.*, 2022; Meng *et al.*, 2019]. Combined with a
83 sliding window approach, we are able to instantly capture the
84 temporal frequency changes in the signal using an encoder
85 equipped with attention based separate decoders for the con-
86 tinuous probabilities of P and S waves. REAVER not only
87 significantly enhances detection speed, needing only 0.08
88 seconds of the waveform to predict P-waves with up to 70%
89 faster than existing approaches, but also achieves a higher
90 classification accuracy of 98.81%. The proposed approach
91 was implemented into a web-based EEWs that allows users
92 to monitor seismic stations for real-time earthquake warnings
93 or to analyze past earthquake waveforms (cf. Fig. 1). The
94 source code of REAVER is available at the following GitHub
95 repository¹ along with a demonstration video showing how it
96 works².

97 2 System Overview

98 REAVER is composed of 4 layers: 1) Data acquisition
99 layer that gets real-time and historical waveforms, 2) Pre-
100 processing layer which divides the signal into overlapping
101 windows and computes the Mel-Spectrogram for each win-
102 dows, 3) Model layer which predicts the continuous probabili-
103 ties of P and S waves, and 4) Warning layer which publishes
104 warnings to subscribers when the detection of P or S waves
105 exceeds a threshold to take an instant response (cf. Fig. 2).

106 2.1 Data Acquisition Layer

107 The data acquisition layer is responsible for collecting the his-
108 torical waveform data for model training and real-time data
109 from seismic stations for inference. For real-time data ac-
110 quisition, the user chooses a network and a station from an

¹<https://github.com/InformationServiceSystems/pairs-project/tree/main/Modules/CrisisImaginator/REAVER>

²<https://www.youtube.com/watch?v=PIRmRzfHn-K>

inventory provided by Obspy³ - a python package for seismol- 111
ogy. The chosen variables are encapsulated within a request 112
to acquire real-time data from IRIS real-time server⁴ for later 113
processing. For model training, the layer collects historical 114
waveforms data from STEAD [Mousavi *et al.*, 2019], which 115
contains 1.2 million earthquake and noise waveforms with a 116
sampling rate of 100 Hz. Each waveform is represented as 117
3-channel time-series $X_c(t)$ where c corresponds to the ver- 118
tical (Z), north-south (N), and east-west (E) components of 119
seismographs. 120

121 2.2 Pre-Processing Layer

122 The pre-processing layer receives the raw waveform and 123
slices it into overlapping windows across each channel. Un- 124
like [Mousavi *et al.*, 2020; Zhu and Beroza, 2019] which use 125
the full raw waveform, the slicing approach allows a more de- 126
tailed and continuous analysis of the signal over time, which 127
is crucial for real-time EEWs. Formally, we segment each 128
channel into overlapping windows as follows:

$$S = W - \left(\frac{O}{100} \times W \right), \quad N = 1 + \left\lfloor \frac{L - W}{S} \right\rfloor \quad (1)$$

129 where S is the step size, W is the window length, $\frac{O}{100}$ 130
is the overlap percentage, L is the length of each channel in 131
the signal, and N is the total number of windows per channel. 132
The output is a list of windows $w_i^c = X_c[s_i : e_i]$ for each 133
channel c and window i , where s_i and e_i are the start and 134
end indices of the i^{th} window, respectively. Instead of using 135
the raw waveform of signal amplitudes, we convert the sig- 136
nal in each window into its Mel-Spectrogram representation 137
by computing the Short-Time Fourier Transform (STFT) as 138
follows: 139

$$\text{STFT}\{x(t)\}(m, \omega) = \sum_{n=-\infty}^{\infty} x(n) \cdot w(n - m) \cdot e^{-j\omega n} \quad (2)$$

140 where $w(n)$ is the window function, m is the time index, and 141
 ω is the frequency index. Then, a set of k triangular filters 142
 $\{H_k(m)\}$ is applied to the STFT, where each filter corre- 143
sponds to a Mel frequency. The log Mel-Spectrogram for 144
each window is then obtained as:

$$w_i^c = \log \left(\sum_m |\text{STFT}\{w_i^c(t)\}(m, \omega)| \cdot H_k(m) \right) \quad (3)$$

³<https://github.com/obspy/obspy/wiki/>

⁴<https://www.iris.edu/hq/sage>

144 where c is the channel index.

145 2.3 Model Layer

146 The model layer takes input the Mel-Spectrogram windows
 147 for each channel w' and passes it to the REAVER model.
 148 The model is composed of a multi-stage encoder, an atten-
 149 tion layer for each stage, and two separate decoders for P and
 150 S waves. The encoder consists of 4 stages, where each stage
 151 S_i is defined as a sequence of two blocks. Each block applies
 152 a Conv2D layer followed by BatchNorm2d and ReLU acti-
 153 vation function. Given the set of Mel-Spectrogram windows
 154 W' , the operation of a single block can be represented as:

$$\text{Block}(W') = \text{ReLU}(\text{BatchNorm2d}(\text{Conv2d}(W')))$$

155 Therefore, each stage in the encoder can be expressed as
 156 the composition of two such blocks:

$$S_i = \text{Block}(\text{Block}(W'_i))$$

157 where W'_i is the output from the previous stage or the input
 158 to the encoder for $i = 1$. Subsequently, P Decoder and S
 159 Decoder each apply spatial self-attention to the outputs from
 160 each encoder stage, which can be written as:

$$\text{Attn}(S_i) = \text{Conv2d}(S_i \odot \sigma(\text{Conv2d}(S_i)))$$

161 where σ denotes the sigmoid function and \odot represents
 162 element-wise multiplication. The attention mask generated
 163 by the sigmoid function modulates the feature map for each
 164 branch to focus on relevant features for P and S waves sep-
 165 arately. Each decoder consists of sequences of such $\text{Attn}()$
 166 layers followed by upsampling and convolution operations.
 167 Formally, for each stage S_i of the encoder, the corresponding
 168 decoder block output can be represented as:

$$D_i = \text{Upsample}(\text{Conv}(\text{Attn}(S_i)))$$

169 where D_i is the output of the i -th decoder block. Finally, the
 170 continuous probabilities for P and S wave, denoted as P_p for
 171 the P Decoder and P_s for the S Decoder, can be expressed as:

$$P_p = \text{FC}(\text{Upsample}(\text{GlobalAvgPool}(D_P)))$$

$$172 \quad P_s = \text{FC}(\text{Upsample}(\text{GlobalAvgPool}(D_S)))$$

173 where D_P and D_S are the aggregated outputs of the P De-
 174 coder and S Decoder blocks, respectively. We utilize Bina-
 175 ryCrossEntropy loss for supervising both P_p and P_s .

176 2.4 Warning Layer

177 The warning layer evaluates the probabilities P_p and P_s from
 178 the model layer and issues warnings to subscribers, includ-
 179 ing individuals or government entities, when $P_p > P_{\text{thr}}$ or
 180 $P_s > S_{\text{thr}}$, aiming for timely Earthquake response. P_{thr} and
 181 S_{thr} are hyperparameters which are set to 0.7 upon extensive
 182 experiments to optimize the precision-recall trade-off.

183 3 Evaluation

184 To evaluate our method we use a dataset consisting of 51,510
 185 earthquakes and 11,773 noise waveforms from STEAD. We
 186 simulate real-time detection by applying a 4-second sliding
 187 window with 99% overlap before the P- and S-wave arrival

188 times. We compare our method against classical STA/LTA
 189 method [Choubik *et al.*, 2020], and deep learning meth-
 190 ods Phasenet [Zhu and Beroza, 2019] and EQTransformer
 191 [Mousavi *et al.*, 2020] which were originally trained using
 192 30- and 60-second windows respectively. We apply the same
 193 sliding window configuration across all methods for a fair
 194 comparison. In our evaluation, we prioritize two critical di-
 195 mensions of earthquake detection performance: the speed of
 196 P-wave detection and the accuracy of distinguishing between
 197 earthquake and noise waveforms. Speed of detection is as-
 198 sessed through Δt , representing the time difference between
 199 the algorithm’s detection of the P-wave and its actual occur-
 200 rence. Additionally, we evaluate classification accuracy, mea-
 201 suring each method’s ability to correctly identify earthquake
 202 waveforms against impulsive noise.

Table 1: Performance comparison of P-wave detection time statis-
 tics, showing the mean time difference Δt_{mean} , standard deviation
 $\sigma_{\Delta t}$, median Δt_{median} , 25th percentile (Q1) $\Delta t_{25\%}$, and 75th per-
 centile (Q3) $\Delta t_{75\%}$.

Method	Δt_{mean} (s)	$\sigma_{\Delta t}$ (s)	Median (s)	Q1 (s)	Q3 (s)
Phasenet	1.67	2.01	0.83	0.59	1.93
Eqtransformer	3.73	4.48	1.62	1.20	4.00
STA/LTA	0.27	0.31	0.15	0.04	0.40
REAVER	0.08	0.16	0.04	0.03	0.12

Table 2: Classification performance on the testing dataset.

Method	Precision	Recall	F1 Score	Accuracy (%)
Phasenet	0.98	0.96	0.97	95.46
Eqtransformer	0.99	0.91	0.95	92.50
STA/LTA	0.96	0.85	0.89	85.56
REAVER	0.99	0.98	0.99	98.81

203 Table 1 shows the distribution statistics of Δt over the test-
 204 ing dataset for all the methods. We can observe that REAVER
 205 significantly enhances detection timeliness, improving by
 206 70% over STA/LTA and around 95% over Phasenet and Eq-
 207 transformer in mean detection time difference (Δt_{mean}). In
 208 Table 2, we show the classification performance of differen-
 209 tiating between earthquake and noise waveforms, recording a
 210 correct detection when either a P or S wave was detected in
 211 the waveform. We observe that REAVER outperforms other
 212 methods in accurately detecting earthquakes with overall ac-
 213 curacy 98.81%.

214 4 Conclusion

215 In this paper, we proposed REAVER, a novel method for real-
 216 time earthquake prediction utilizing attention-based sliding-
 217 window spectrograms. Our evaluation demonstrates that our
 218 method not only achieves high accuracy in differentiating
 219 earthquakes from noise, but also offers faster detection times
 220 compared to existing methods. Furthermore, REAVER’s
 221 web-based implementation allows for real-time earthquake
 222 monitoring and historical waveform analysis, making it a
 223 valuable tool for both individuals and professionals in seis-
 224 mology.

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