## Some Basics for Search Methods

Search paradigms

Some representation paradigms

Language Technology

## SEARCH PARADIGMS

Breadth-first

Expanding the search tree chronologously, level by level

Depth-first

Expanding the search tree chronologously, branch by branch

**Best-first** 

Expanding the search tree opportunistically, at position considered "best"

## BREADTH-FIRST SEARCH

**Properties** 

No heuristic knowledge required Always finds optimal solution Exponential complexity Exponential storage requirement

Use

Frequent use, but in highly modified forms Speech analysis, syntactic processing, machine translation, ...

## DEPTH-FIRST SEARCH

#### **Properties**

Heuristic knowledge exploitable

Finding a solution depends on choice of depth (none, optimal, suboptimal)

**Complexity depends on exploitation of infomation** 

(cut-offs possible, depending on properties of evaluation scores)

Linear storage requirement

Ordering of expansions may be essential, if cut-offs possible

**Iterative deepening possible** 

### Use

Frequent use in modified forms, some use within homogeneous representations Compound processes, constraint systems

## CHIRONOLOGOUS SEARCHIES

#### **Extensions**

**Combination of breadth- and depth-first** 

**Speculative search space limitations** 

- Limiting the number of alternatives considered (*beam search*)
- No guarantee of optimal solution
- No solution guarantee at all
- Large search spaces with reasonable intermediate information manageable

#### Use

Beam search very widely used

**Combinations for compound processes, according to domain preferences** 

### BEST-FIRST SEARCH (A\*)

### **Properties**

Homogenous evaluation of problem states required Concept of optimal path costs:  $f^*(n) = g^*(n) + h^*(n)$ Heuristic estimates of optimal path costs: f(n) = g(n) + h(n)

- g(n) ... minimal path costs found to current state
- h(n) ... estimated path costs from current state to goal state

Node associated with best heuristic score is expanded next

Theorem: If  $h(n) \le h^*(n) \forall n$ , A\* is *admissible* (finds optimal solution) Use

**Machine translation** 

**Specific subprocesses** 

# EXAMPLE - BEST-FIRST SEARCH (GENERATING REFERRING EXPRESSIONS)

**Problem description** 

Identifying *a set* of referents with *one* expression

Accumulating descriptors, including boolean combinations

### Search space modeling

**Initial state – empty description** 

**Goal state – a distinguishing description (some are optimal)** 

**Intermediate state – a non-distinguishing description** 

#### Search space exploration – Description expansion

*All* intermediate results can be expanded further – these are the nodes (only the full expression in the incremental algorithm)

### EXAMPLE - BEST-FIRST SEARCH (III)

#### **Evaluation function**

n ... node associated with some partial description

f(n) = (minimal) number of descriptors for a distinguishing description

g(n) = number of descriptors used in partial description generated so far in n

h(n) = complexity of descriptor combinations still unused at state n

#### Search tree expansion

Build successors of node evaluated best, if none yet unexplored,

with minimally complex descriptor combination still available there

Choose as the next node the one among open ones with best score that have

- minimum number of potential distractors still to be excluded

- minimum complexity of descriptor combinations still unused

# SEARCH OPTIMIZATIONS - CUT-OFFS (I) (EXPLOITING ADMISSIBILITY)

Effect of admissibility

Algorithm terminates if no more nodes are worth expanding (heuristic score is not better than proved value of a solution)

Value Cut-off – Realization of consequence of admissibility

If a solution is found (f(n)), its score is compared to each node

If for that node partial score plus the optimistic estimate is below the score of the best solution found so far  $(g(n_i) + h(n_i) \ge f(n))$ 

Then this node is closed

# SEARCHI OPTIMIZATIONS - CUT-OFFS (II) JUSTIFIED BY GOAL REQUIREMENTS OR ASSUMPTIONS

### Dominance Cut-off

### Applicable to – Sibling nodes with

- partial descriptions excluding the same potential distractors
- the same set of descriptors available

The node with partial description evaluated worse is closed (worse g(n))

### Complexity Cut-off

Description considered too complex not generated, may not yield a solution

### Expression Cut-off

"Mixed" disjunctions excluded ("car or red"), also may not yield a solution

## ASSUMPTIONS

### Value Cut-off

Descriptors map one-to-one onto surface expression components Modification of simple counting possible (but must still be monotone)

Dominance Cut-off

**Compositionality of expressions** 

### Complexity Cut-off

**Complex expressions impractical, task modification required Partitioning the identification task, focus narrowing, then identification** 

### Expression Cut-off

"Mixed" disjunctions impractical, task modification required Partitioning the set of intended referents for separate identification

## COMPARING CUT-OFF MEASURES

#### cut-off measures

	all	value	dominance	complexity	
avg. search tree size	2.2	3.88	2.33	61.64	
max. search tree size	9	71	11	945	
avg. search time (msec)	127.7	168.1	595.0	1133.1	
max. search time (msec)	690	2320	4550	19210	

## REPRESENTATION AS RULES

### Components of a rule

The precondition (if ...) determines the applicability of a rule

The postcondition/action (then ...) determines derived knowledge (applicable actions)

There are two types of rules (distinction essential for commutative rule systems):

- Implications (deduction), deriving the truth of a fact
- *Actions*, which change a state

### Examples

#### **Grammar rules**

Lexical correspondences (in machine translation)

### REPRESENTATION AS CONSTRAINTS

#### Components of a constraint

- A set of variables
- A set of values relating variables to each other

### Constraint problem

Solutions to a constraint problem are assignments of values to variables so that all constraints are fulfilled

### Examples

**Equations (about structure sharing) in unification grammars** 

**Collocation constraints** 

## COMPARISON BETWEEN RULES AND CONSTRAINTS

### Evaluation of information

- Rules are directed, constraints not (that is, rules are more general)
- **Restricted evaluation potential for rules**

### Efficiency

**Restricted interpretation enables more efficient evaluation for rules** 

#### Advantages/disadvantages

- Rules are more modular and easier to adapt
- Constraints enable better information evaluation
- Both are associated with a flow of control that is difficult to understand

### Application areas

- Rules suited for domain with isolated knowledge control over application
- Constraints suited for coherent theories constraint solver as a black box system

# EXAMPLE - CONSTRAINT SYSTEMS (Gardent 2002) (GENERATING REFERRING EXPRESSIONS)

**Problem description** 

Identifying *a set* of referents (S) with *one* expression L

Accumulating descriptors, including *boolean combinations* 

Problem modeling (truth (1+2) and contribution (3))

**1.** All properties applicable to  $S \supseteq$  all properties in L

- **2.** All properties not applicable to  $S \supseteq$  all negative properties in L
- **3.** For all distractors *C* of *S*: properties of *S* other than those of C > 0 or

non-properties of *S* but properties of C > 0

#### Extensions for disjunctions

A disjunction is a distinguishing description for a set of individuals *S* if there is an element in the disjunction identifying covering subsets of *S* 

## EXAMPLE - CONSTRAINT SYSTEMS (III)

Distribution strategy (how to assign values to variables)

Case distinctions over cardinality of *L*, starting with minimal value Algorithm stops once a solution is found

#### Implementation and results

Concurrent programming language Oz (PSE, Uni SB, 1998) Supports set variables ranging over finite sets of integers Runtime example: "the poodle, the jersey, the pitbul, and the poodle" (10 objects, 10 descriptors, sparsely attributed) 1,4 sec

# ATTACKING DEFICITS OF THE INCREMENTAL ALGORITHM – REDUNDANCY (see Gardent 2002)

lescriptors <sup>/objects</sup>	<i>x</i> 1	<i>x</i> <sub>2</sub>	<i>x</i> 3	<i>X4</i>	<i>x</i> 5	<i>x</i> 6
president	•					
secretary		•				
treasurer			•			
board-member	•	•	•	•	•	
member	•	•	•	•	•	•

 $x_1$  and  $x_2$  are the intended referents

Attributes selected: 1) board-member (excluding *x*<sub>6</sub>)

2) ¬treasurer (excluding *x*<sub>3</sub>)

**3**) president  $\lor$  secretary (excluding  $x_4$  and  $x_5$ )

"a board-member, which is the president or the secretary, but not the treasurer"

instead of "the president and the secretary"

# ATTACKING DEFICITS OF THE INCREMENTAL ALGORITHM – DEFICIT – AMBIGUITY (see Gardent 2002)

descriptors <sup>/objects</sup>	<i>x</i> 1	<i>x</i> <sub>2</sub>	<i>x</i> 3	<i>x</i> 4	<i>x</i> 5	<i>x</i> <sub>6</sub>	<i>x</i> <sub>7</sub>	<i>x</i> 8	<i>x</i> 9	<i>x</i> 10 <i>x</i> 11
white	•	•	٠	•	•	•	•	٠	•	•
dog		•						•	•	•
cow			•	•	•	•	•			
big								•	•	•
small						•	•			
medium-sized				•	•					
pitbul										•
poodle									•	
holstein						•				
jersey					•					

# ATTACKING DEFICITS OF THE INCREMENTAL ALGORITHIM – DEFICIT – AMBIGUITY (cont'd)

 $x_5, x_6, x_9$  and  $x_{10}$  are the intended referents

Attributes selected: 1) white (excluding  $x_{11}$ ),

Then several possibilities, e.g.:

**2**) big  $\lor$  cow (excluding  $x_1$  and  $x_2$ )

**3**) Holstein  $\lor \neg$ small (excluding  $x_7$ )

4) Jersey  $\lor \neg$ medium (excluding *x*<sub>4</sub>)

x<sub>3</sub> and x<sub>8</sub> still not excluded

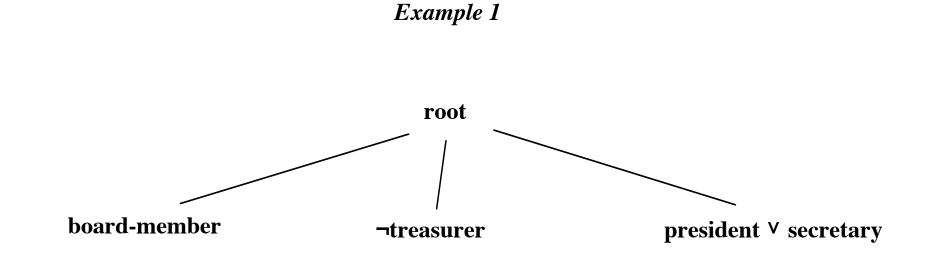
"the white things that are big or a cow, a Holstein or not small,

and a Jersey or not medium" instead of

"the pitbul, the poodle, the Holstein, and the Jersey"

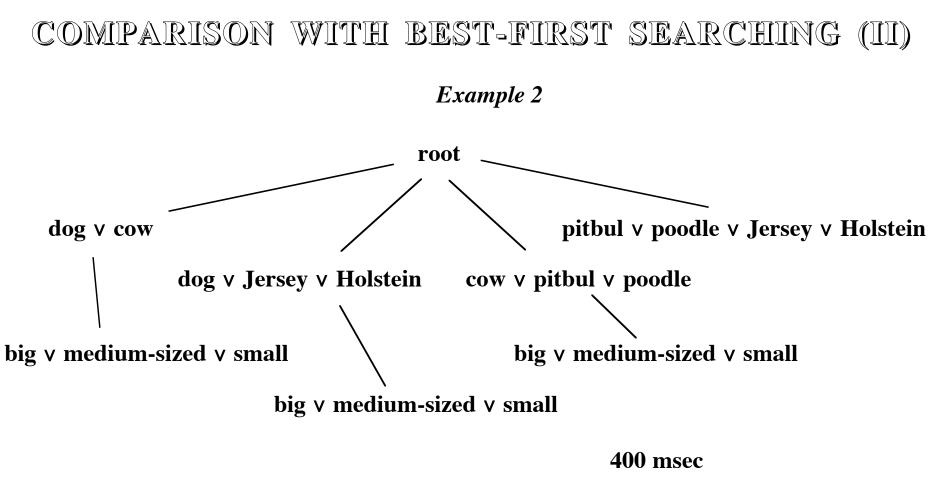
by Gardent's complete constraint-based search (1,4 sec)

# COMPARISON WITH BEST-FIRST SEARCHING (I)



11 msec

(7x faster than (Gardent 2002))



(3,5x faster than (Gardent 2002))